

DTU



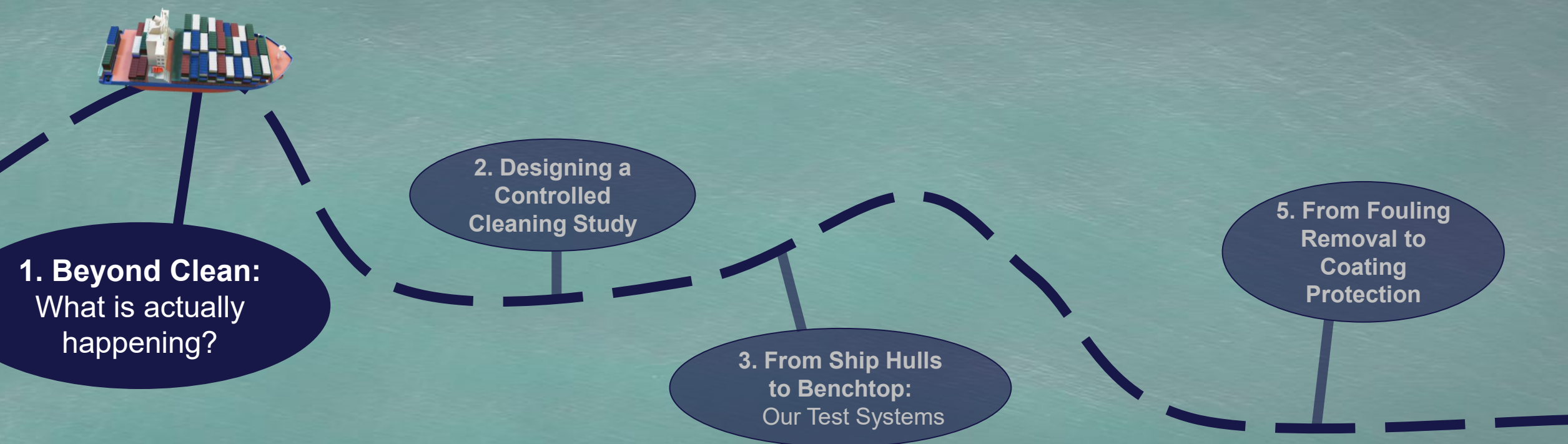
Investigating the Impact of In-Water Cleaning on Coating Performance and Cleaning Efficiency Using a Lab-Scale System

Pascal Alexander Guth

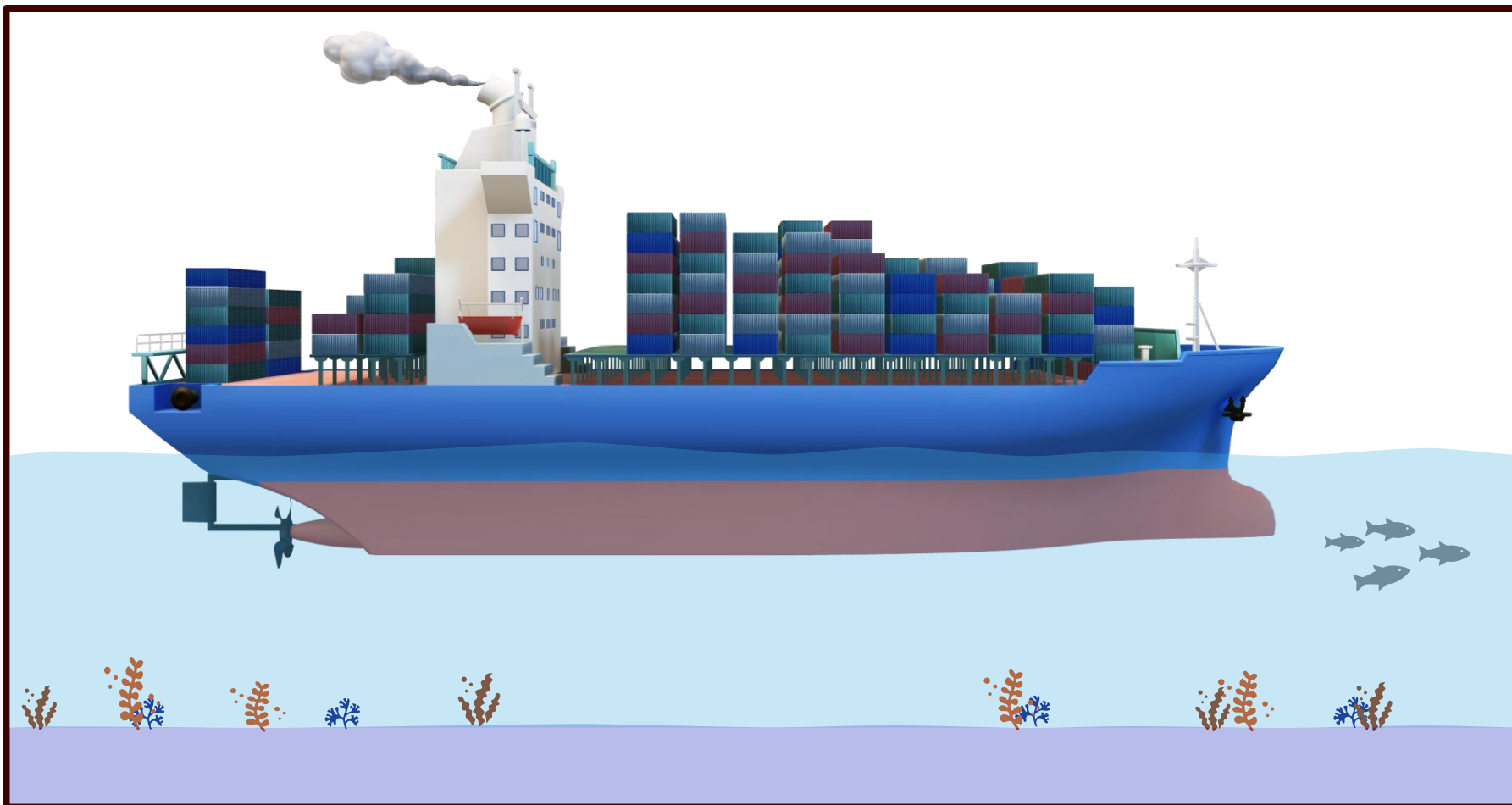
Huichao Bi

Kim Dam-Johansen

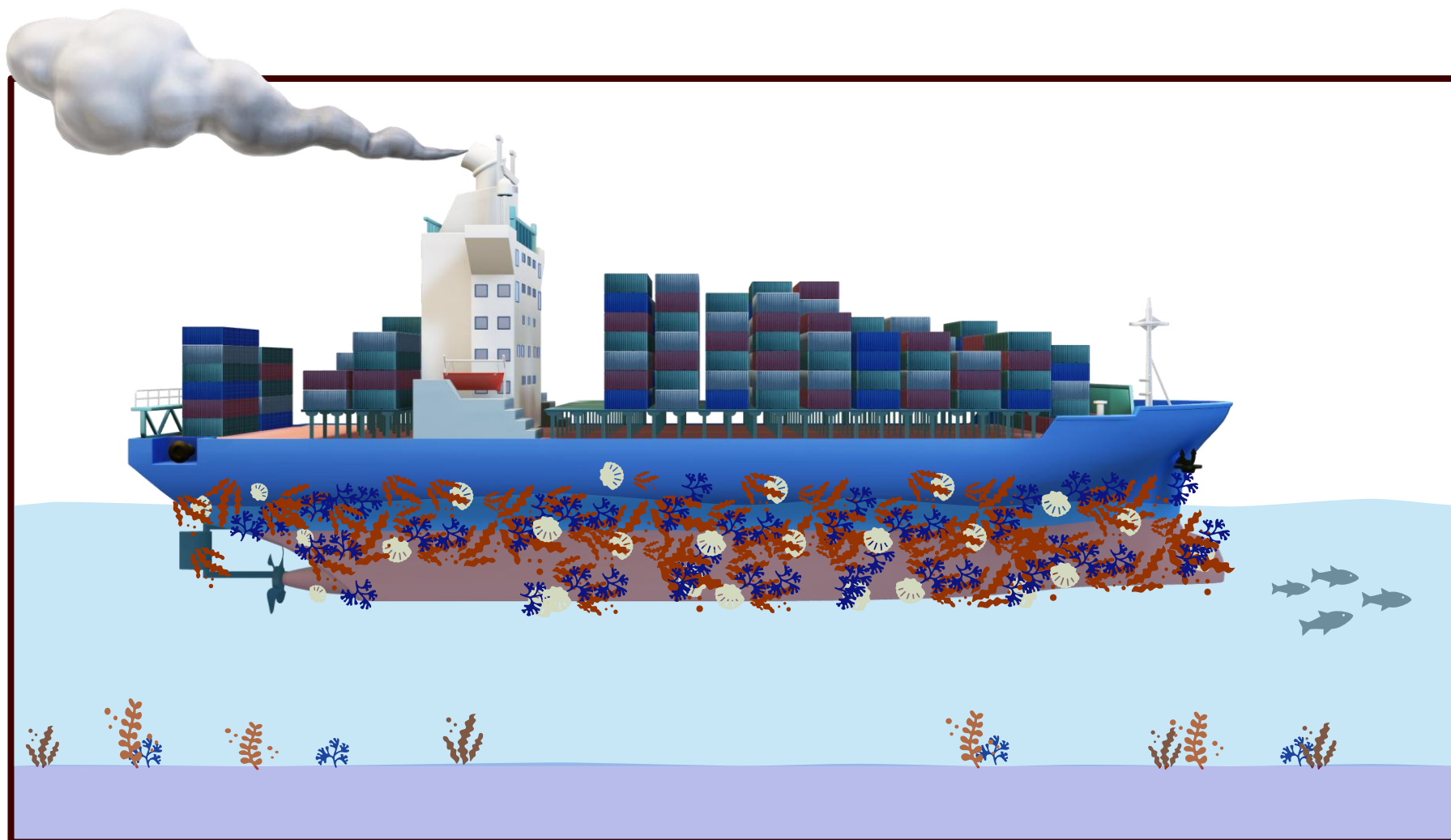
Table of content



Beyond Clean: What is actually happening?



Beyond Clean: What is actually happening?





**How do coatings
respond under
stress?**





How do coatings
respond under
stress?



What is being
released in the
water?





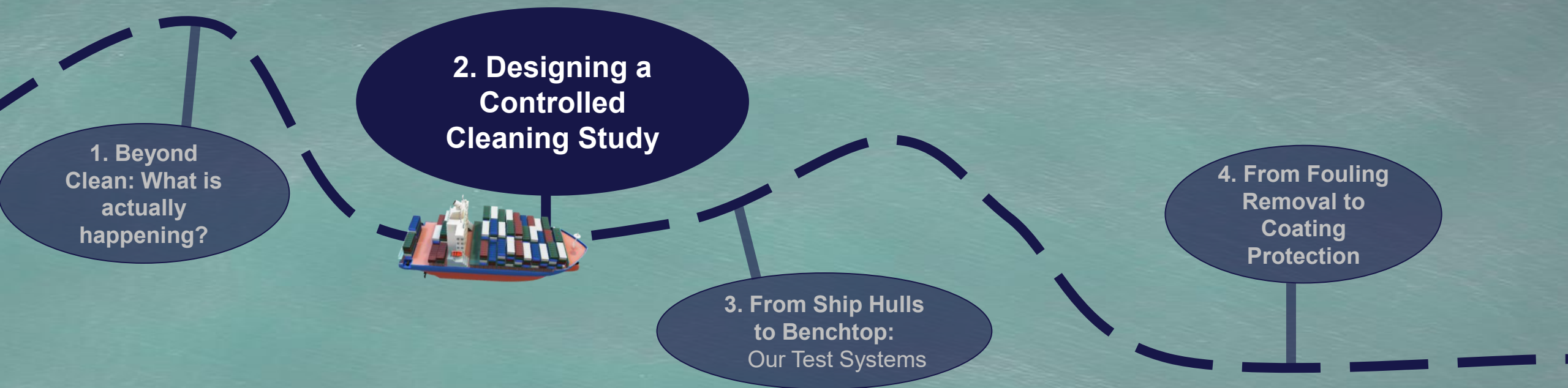
How do coatings
respond under
stress?



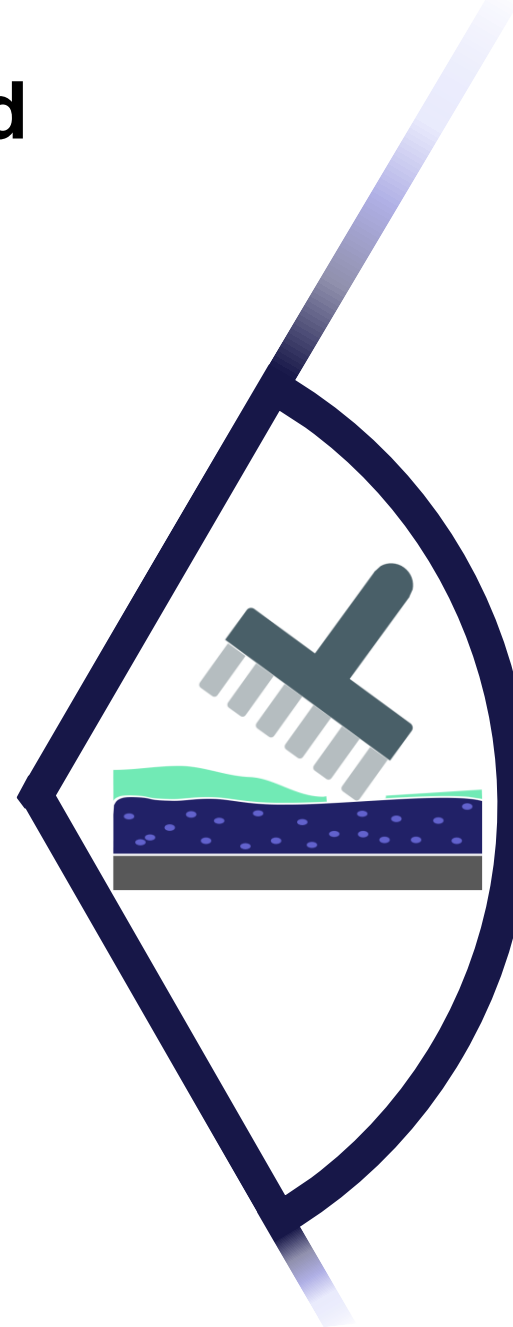
What is being
released in the
water?



How much
force is too
much?



2. Designing a Controlled Cleaning Study



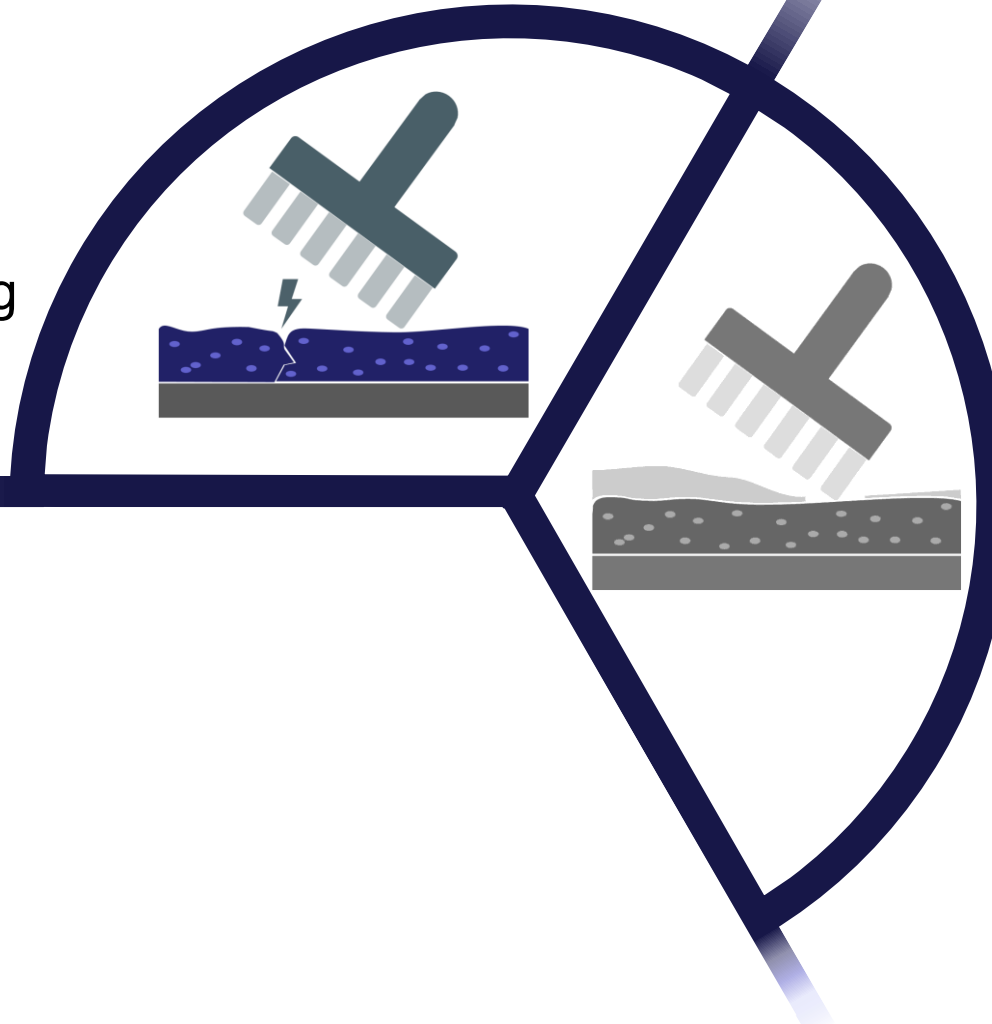
Performance evaluation

- Simulate in-water cleaning under lab conditions

2. Designing a Controlled Cleaning Study

Damage analysis

- Surface degradation
- Compatibility coating – cleaning



Performance evaluation

- Simulate in-water cleaning under lab conditions

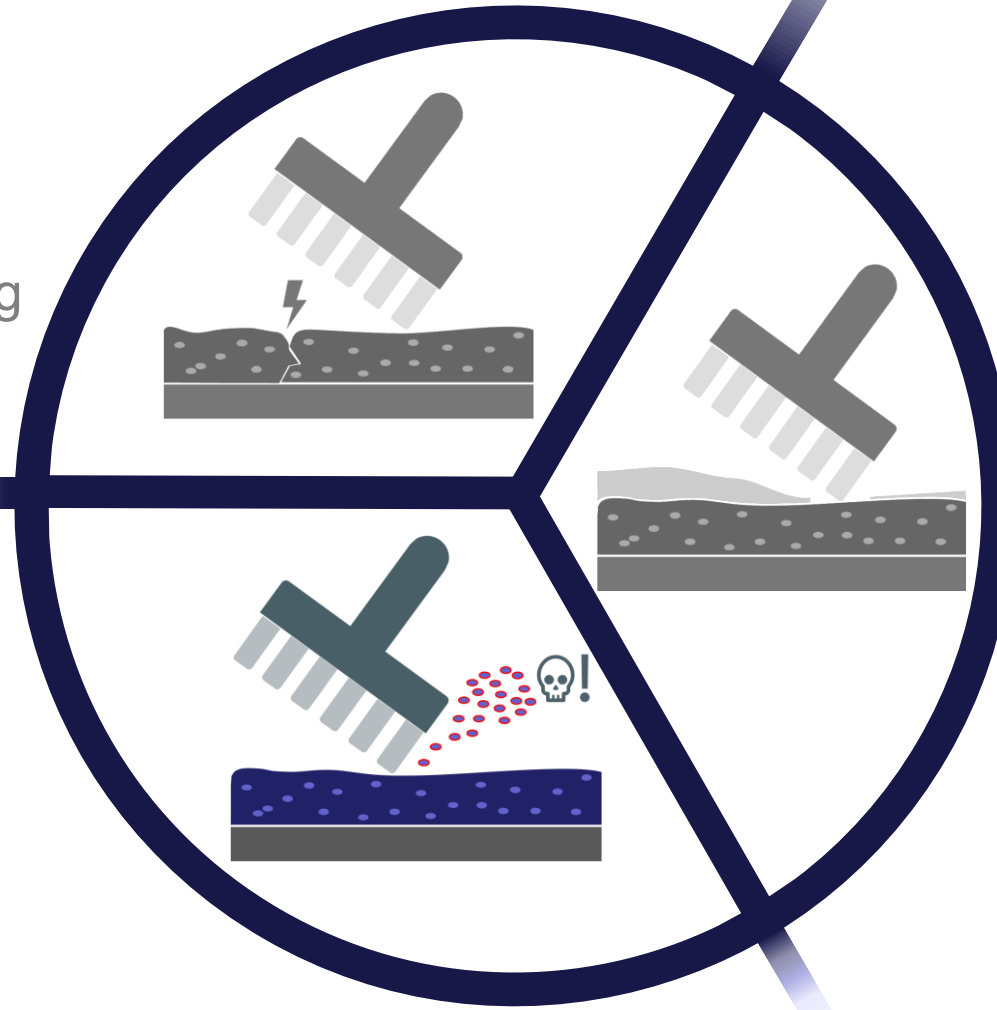
2. Designing a Controlled Cleaning Study

Damage analysis

- Surface degradation
- Compatibility coating – cleaning

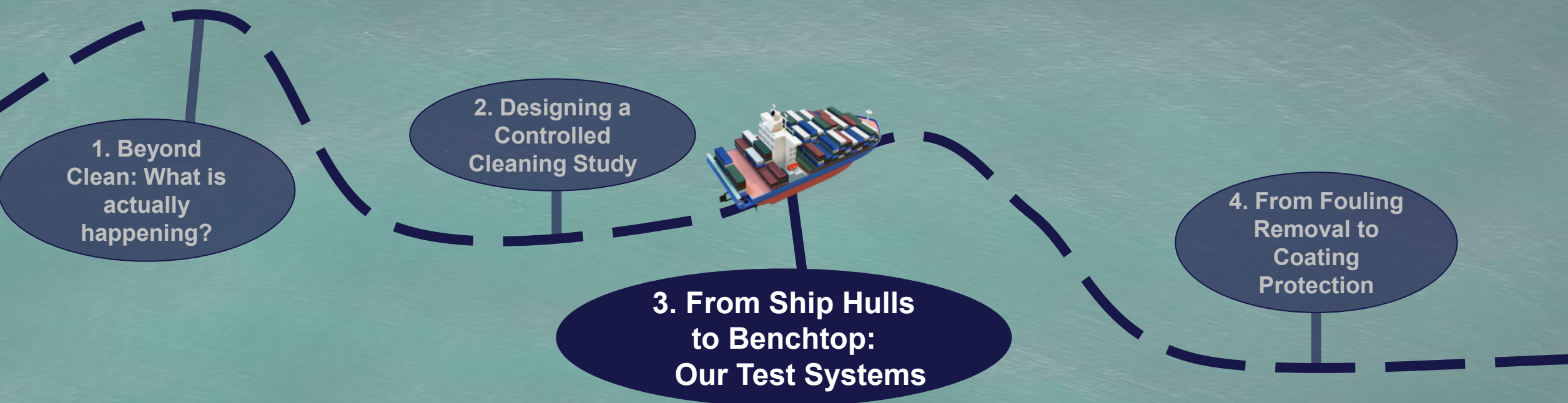
Release analysis

- Biocides
- Microplastic



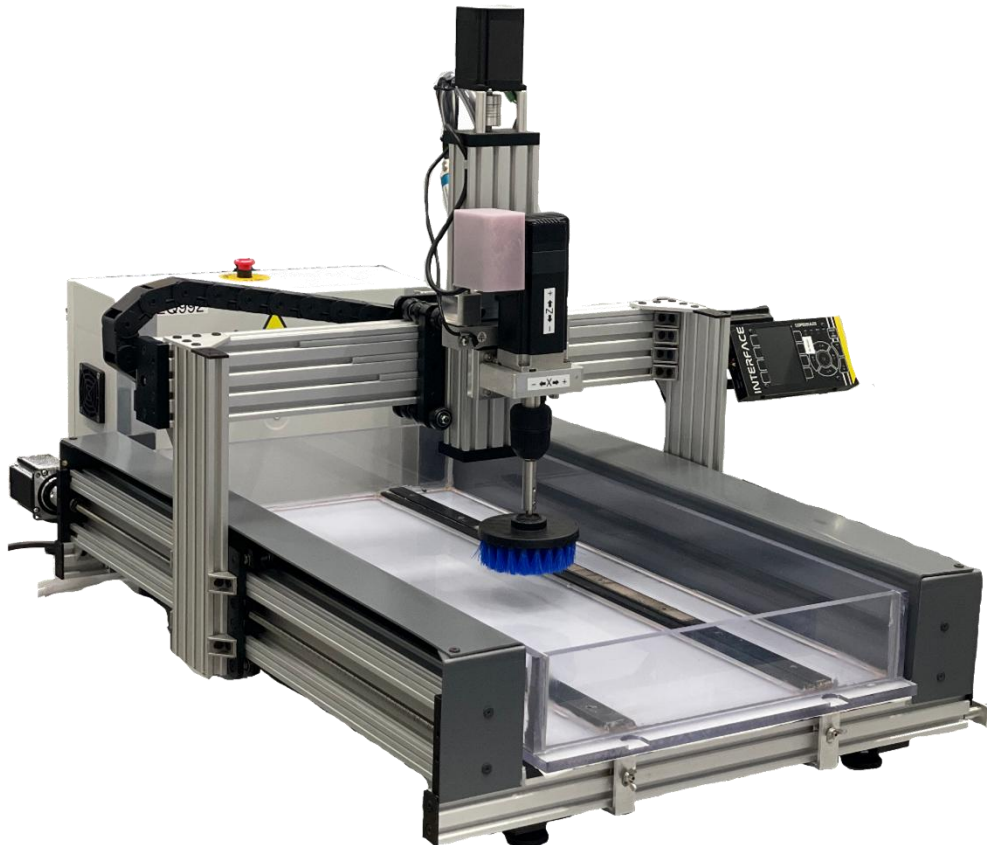
Performance evaluation

- Simulate in-water cleaning under lab conditions



3. From Ship Hulls to Benchtop: Our Test Systems

Automated Underwater Cleaning System (AUCS) – brush cleaning

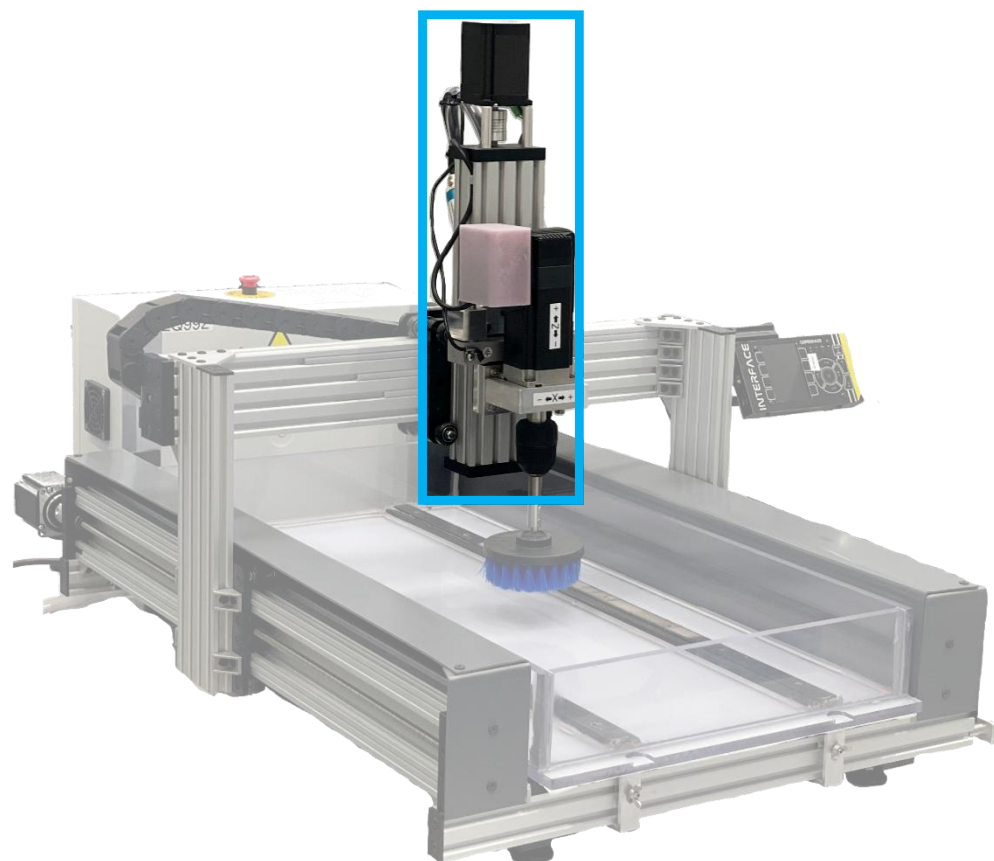


**3-axis gantry for
controlled brush
movement**

**Cleaning tank
with sample
fixation**

3. From Ship Hulls to Benchtop: Our Test Systems

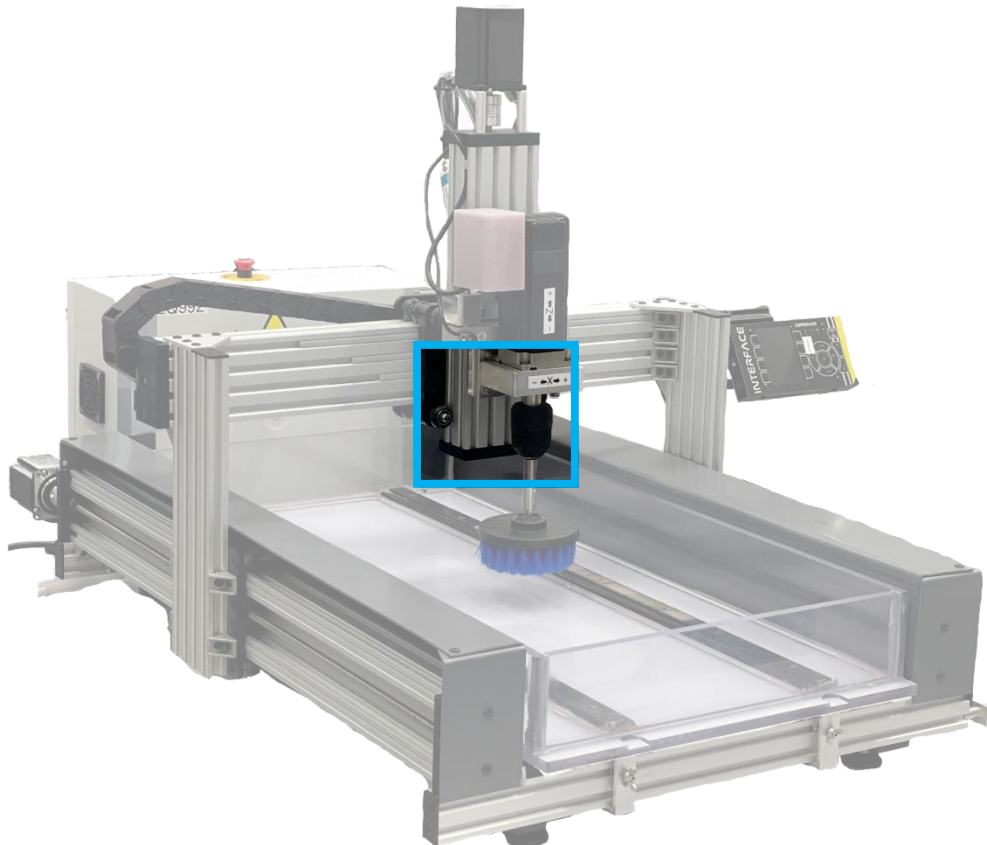
Automated Underwater Cleaning System (AUCS) – brush cleaning



**Adjustable
rotation speed**

3. From Ship Hulls to Benchtop: Our Test Systems

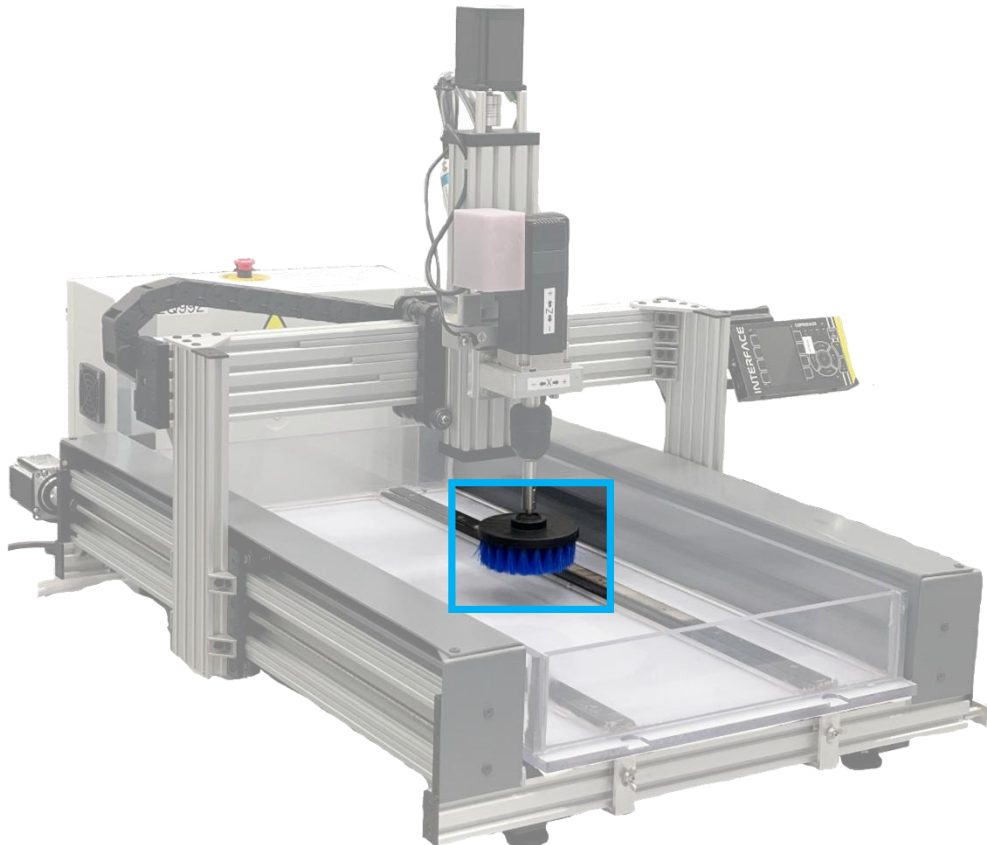
Automated Underwater Cleaning System (AUCS) – brush cleaning



Force sensor

3. From Ship Hulls to Benchtop: Our Test Systems

Automated Underwater Cleaning System (AUCS) – brush cleaning

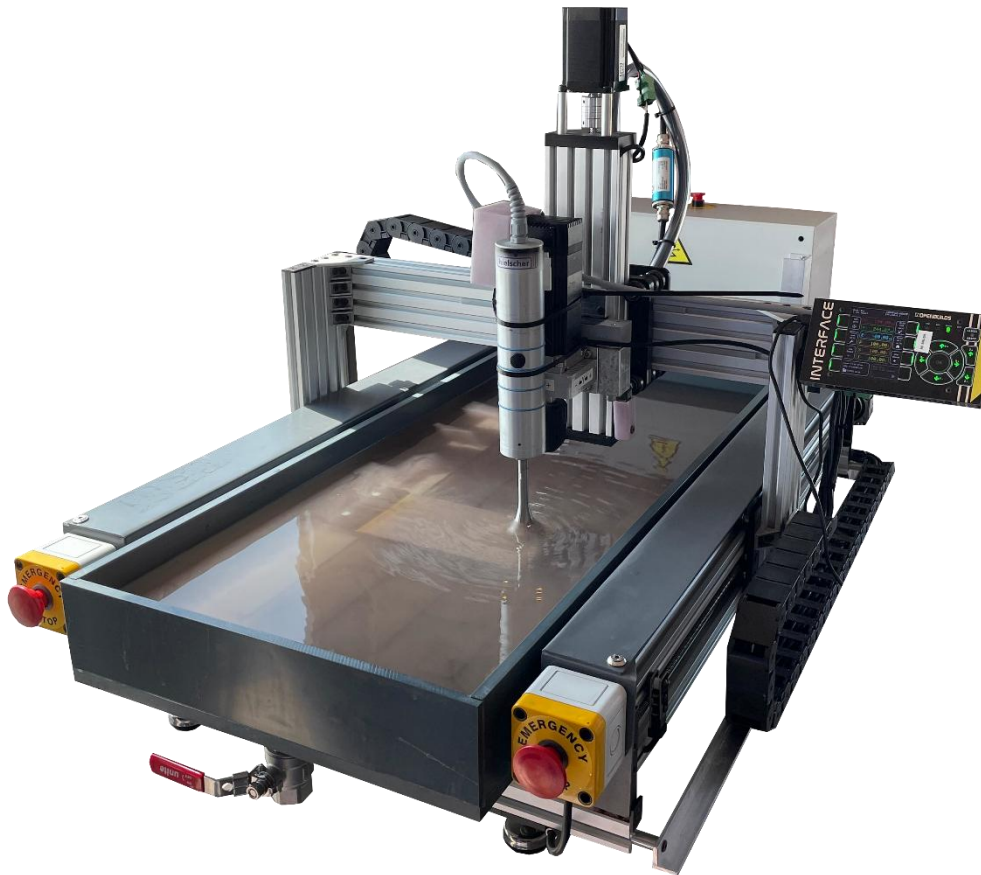


Variable cleaning
brushes



3. From Ship Hulls to Benchtop: Our Test Systems

Automated Underwater Cleaning System (AUCS) – Ultrasonic cleaning

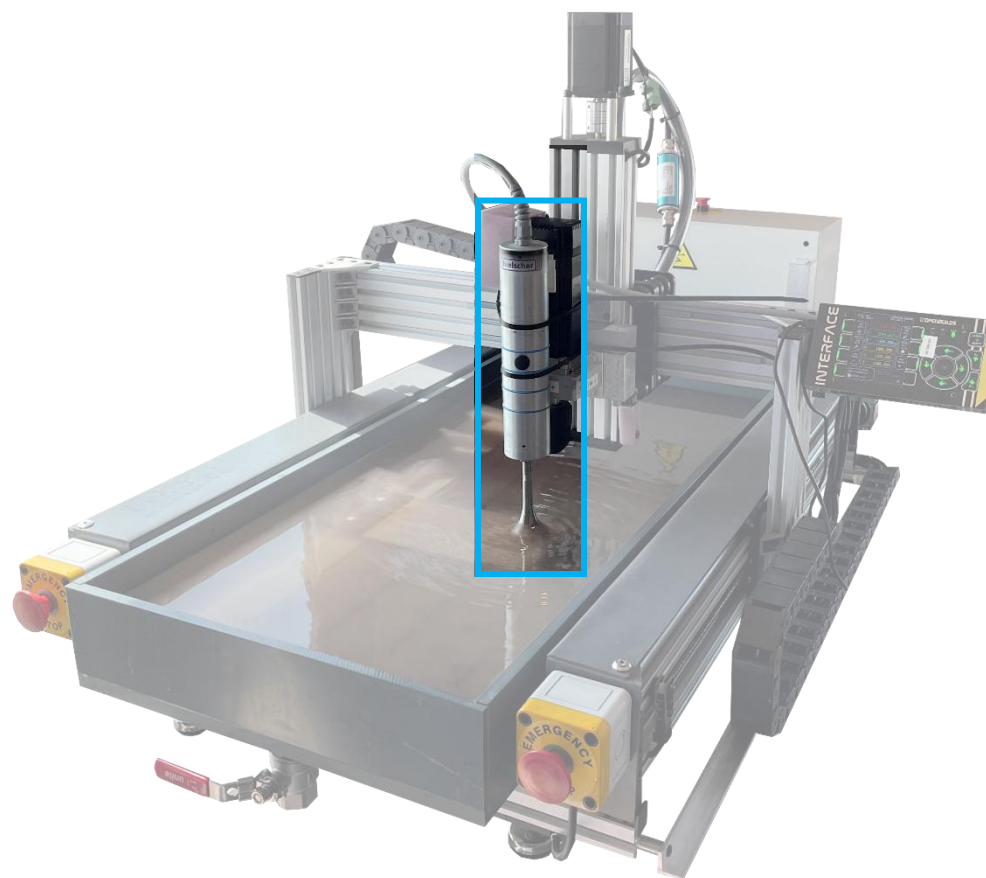


**3-axis gantry for
controlled brush
movement**

**Cleaning tank
with sample
fixation**

3. From Ship Hulls to Benchtop: Our Test Systems

Automated Underwater Cleaning System (AUCS) – Ultrasonic cleaning



Ultrasonic source
+
variable
sonotrodes



3. From Ship Hulls to Benchtop: Our Test Systems

Underwater Water-jet Cleaning System



3. From Ship Hulls to Benchtop: Our Test Systems

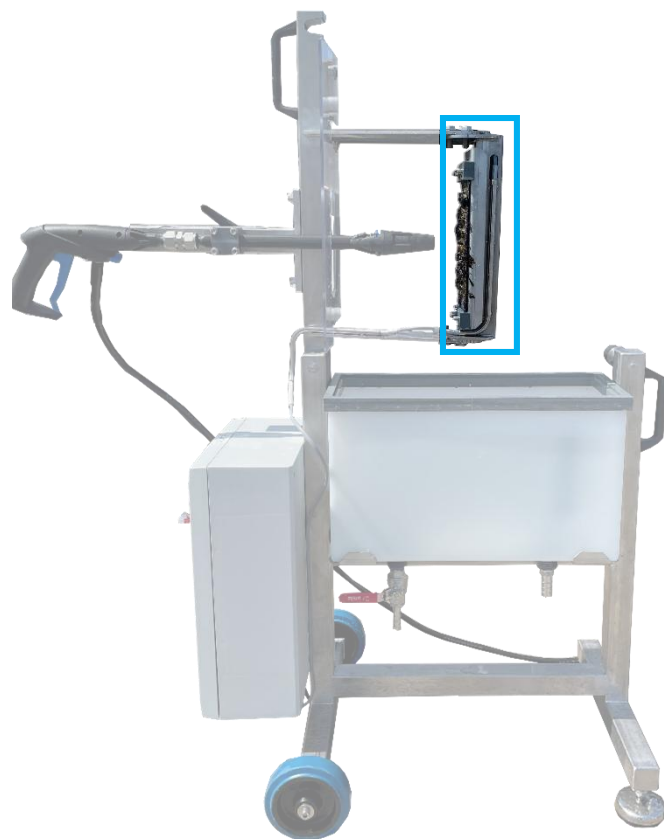
Underwater Water-jet Cleaning System



**Cleaning tank
with overflow
system**

3. From Ship Hulls to Benchtop: Our Test Systems

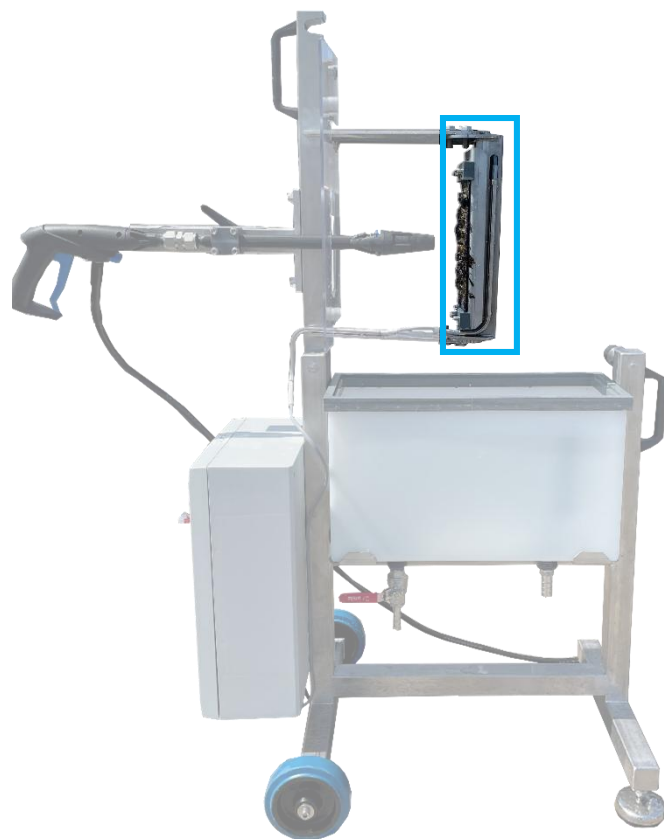
Underwater Water-jet Cleaning System



**Sample holder
with integrated
force sensor**

3. From Ship Hulls to Benchtop: Our Test Systems

Underwater Water-jet Cleaning System

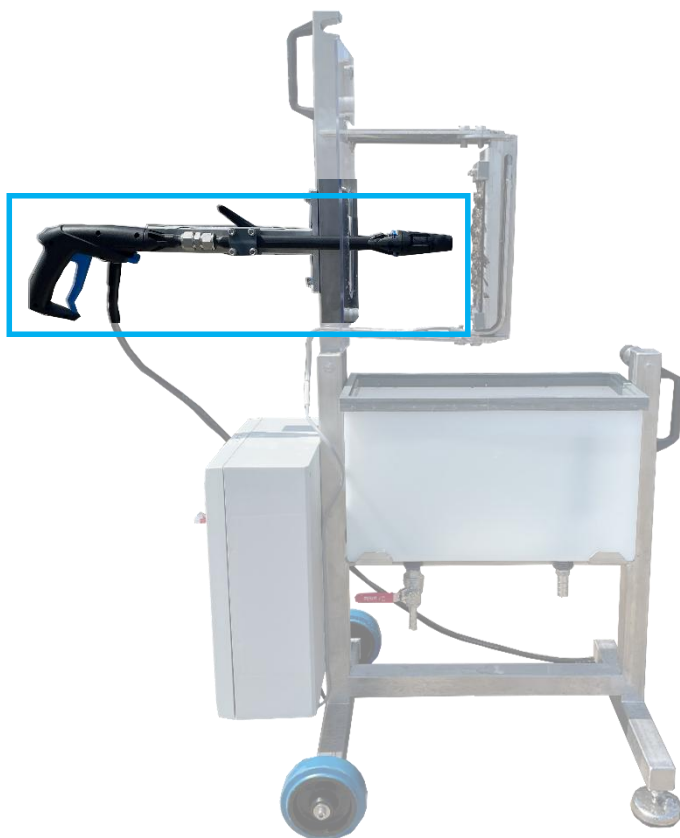


Adjustable angle
nozzle - substrate



3. From Ship Hulls to Benchtop: Our Test Systems

Underwater Water-jet Cleaning System

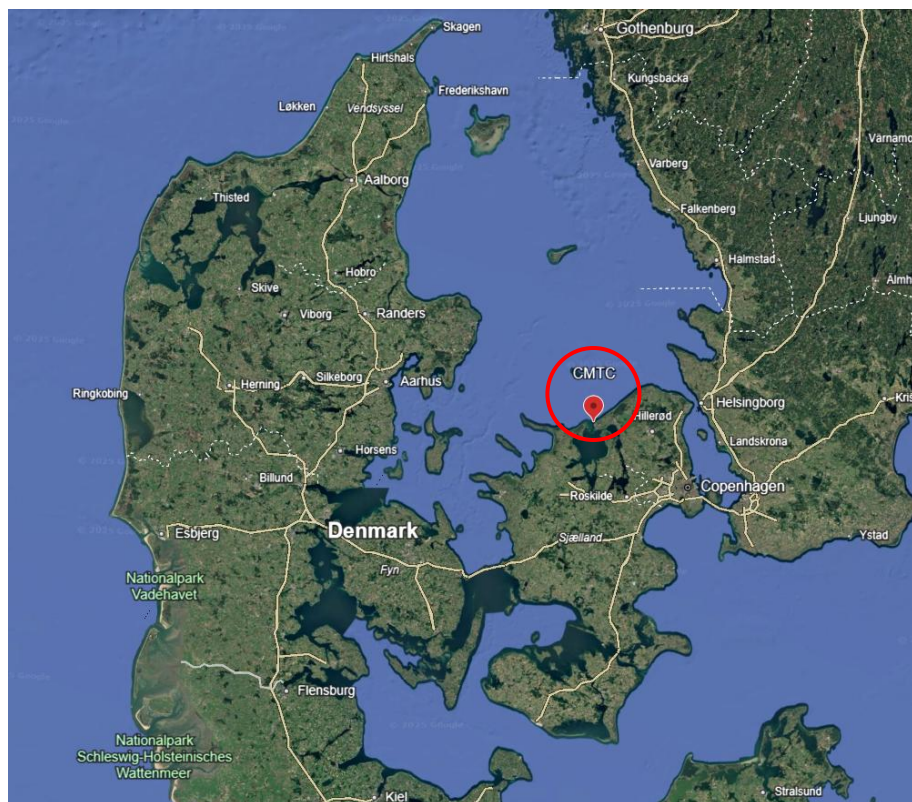


**Water-jet with
exchangeable
nozzle**



3. From Ship Hulls to Benchtop: Our Test Systems

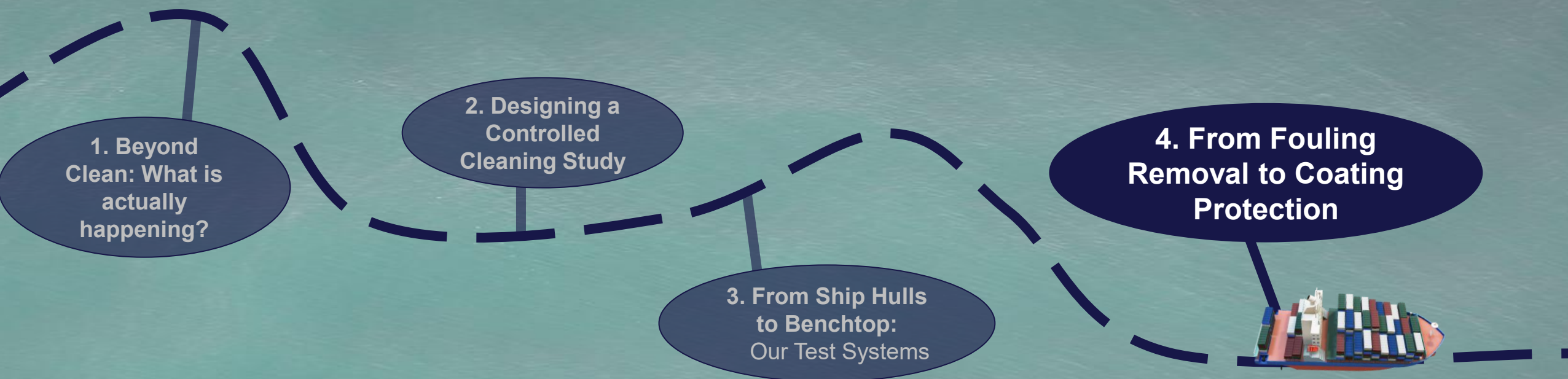
Sample exposure



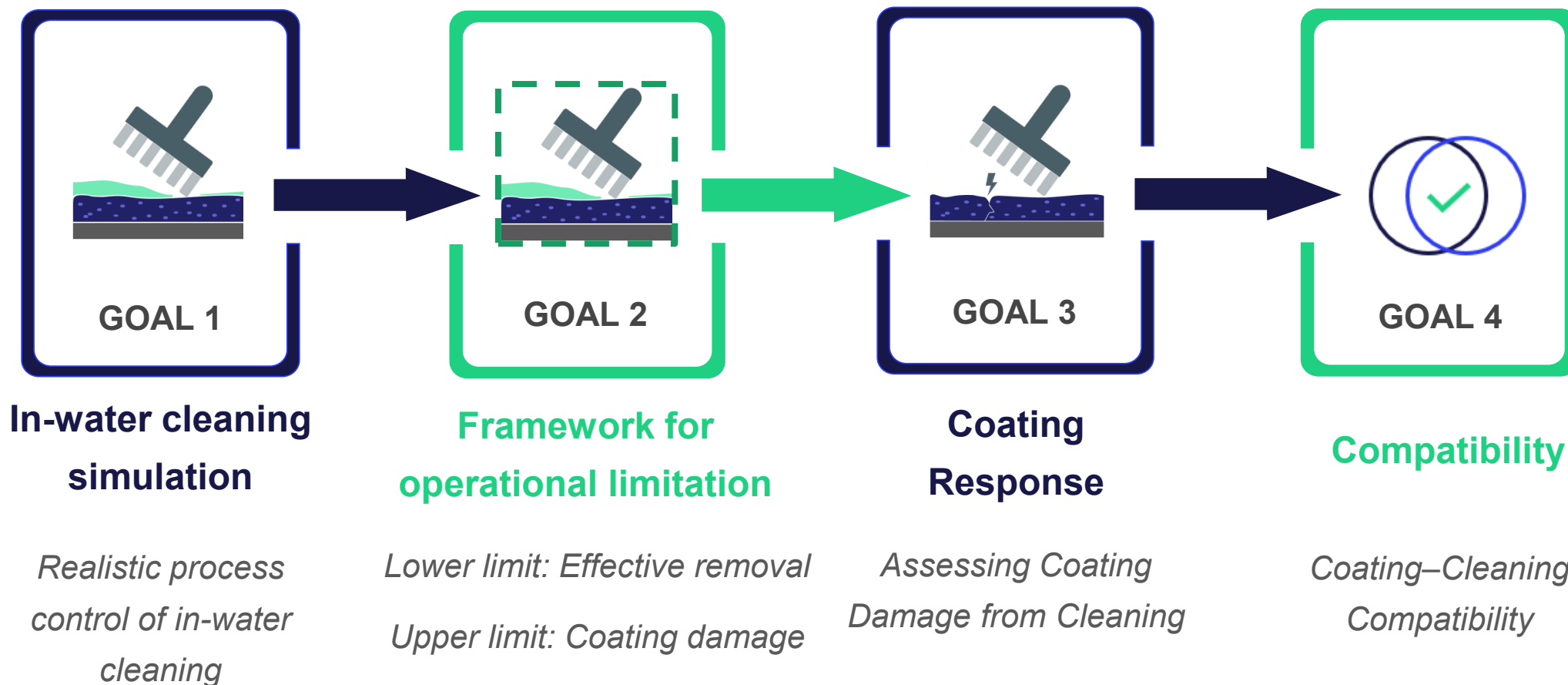
3. From Ship Hulls to Benchtop: Our Test Systems

Sample exposure





4. From Fouling Removal to Coating Protection



Thank you very much for your attention!



Pascal Guth
DTU – CoaST
pasgu@kt.dtu.dk

