

Prologue

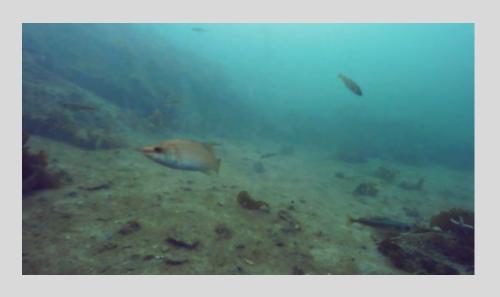








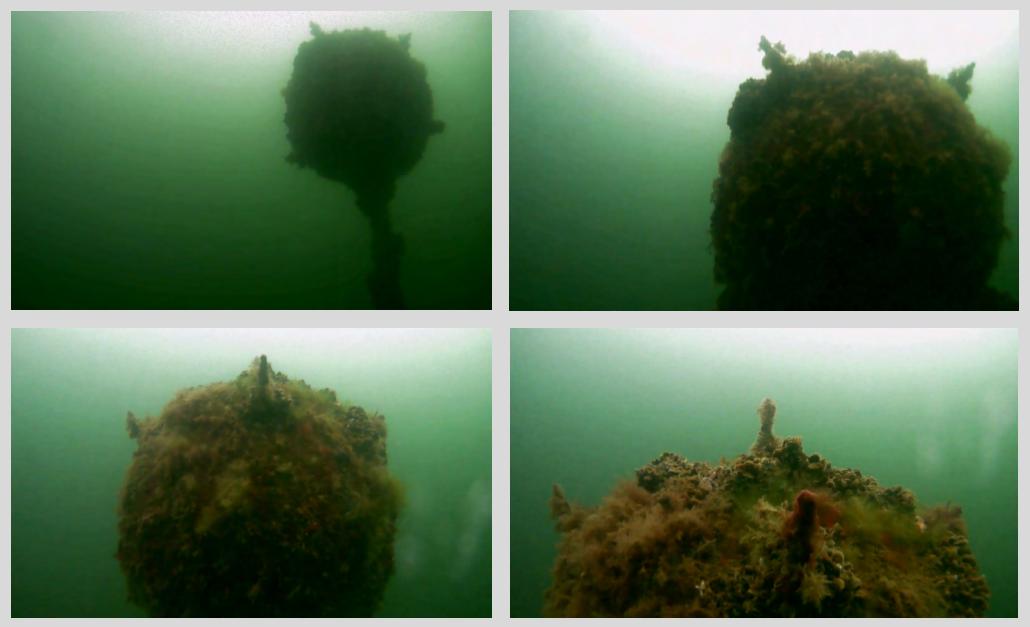




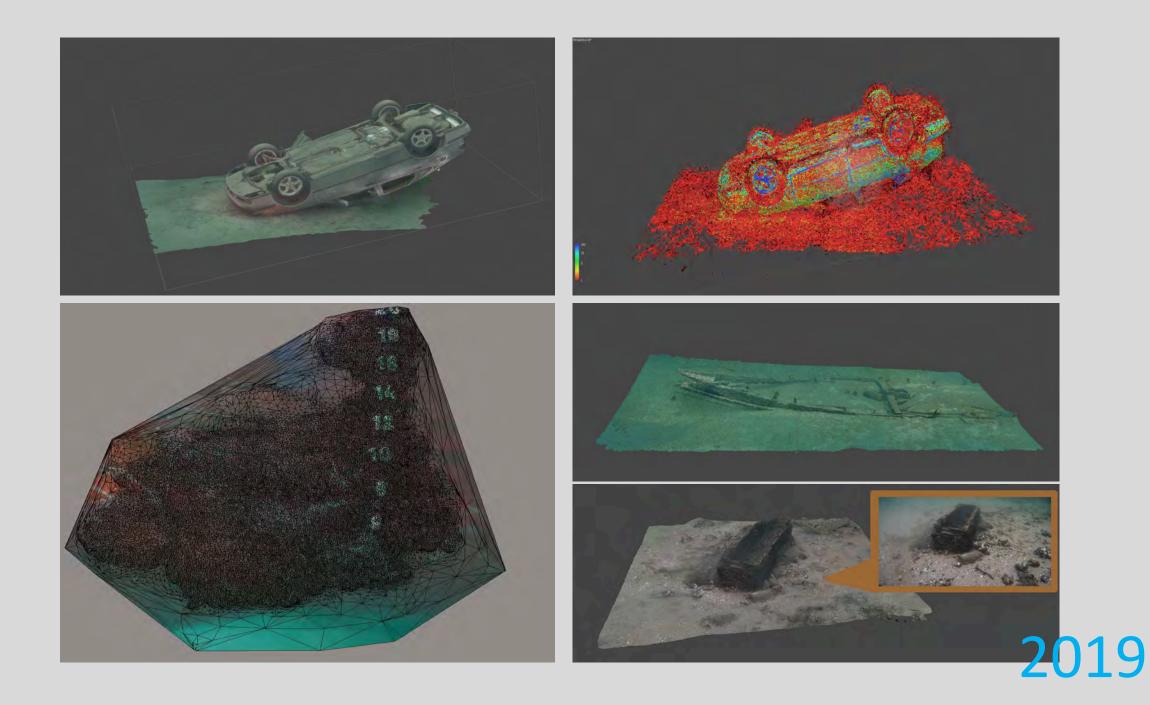


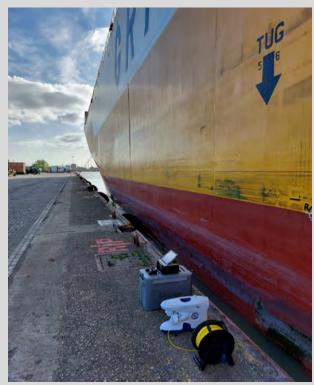






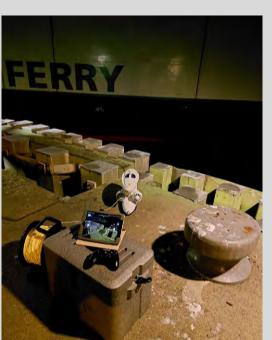


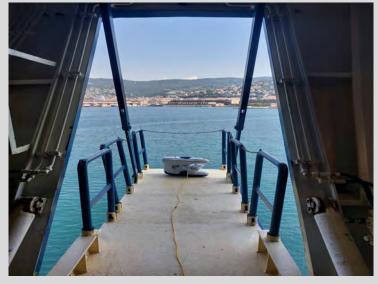








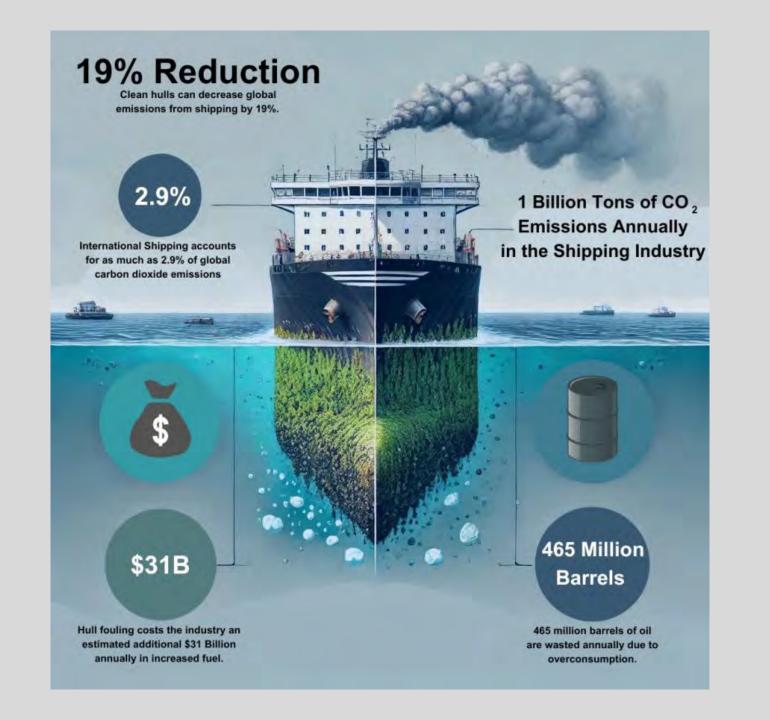


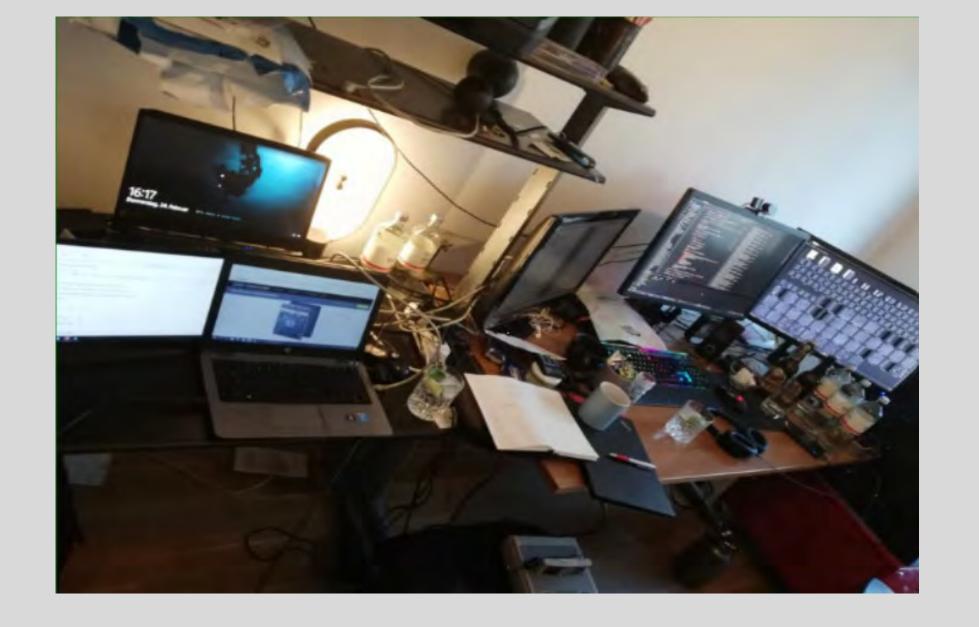




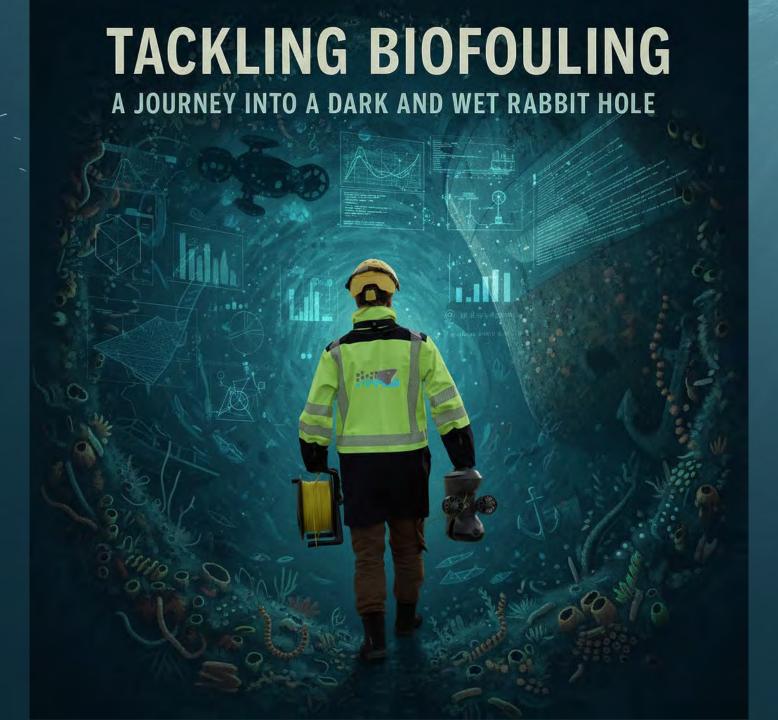












Michael Stein
Vesselity Maritime Analytics

Gothenburg
September 10th 2025

Problem Statement and Intention



Fouling is one of the largest unresolved cost driver in shipping where the absence of one single solution has created a huge and diverse market



In order to understand marine fouling in shipping, you require data... a lot of data to contextualize the impact of risk factors before it attaches to the hull



It is our believe, that AI will close the gap in marine fouling research by allowing to optimize the unseen below the water with data science



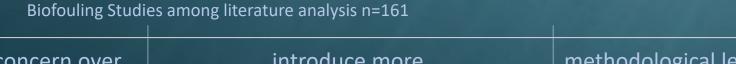
Applying the right AI image segmentation architecture to extract data from visual underwater content is the highest discipline.

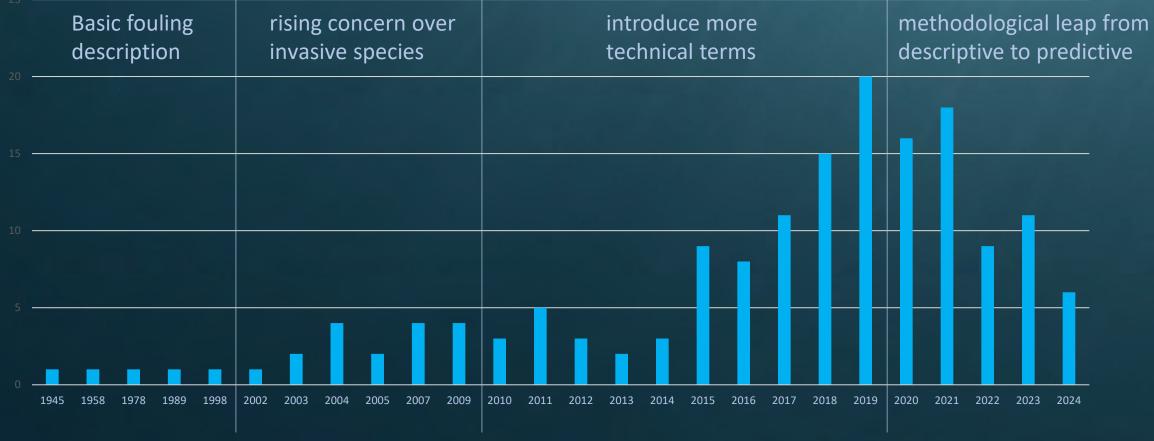
Big Questions About Biofouling

- 1) What kind of fouling is there?
- 2) How much of what fouling is there?
- 3) How does the fouling impact the ship performance?
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 - 1) Can we identify patterns of fouling based on external factors?
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- 5) Is the fouling invasive?
- 6) Can we predict biofouling on ships in advance?

A brief excurse to 80 years of biofouling science







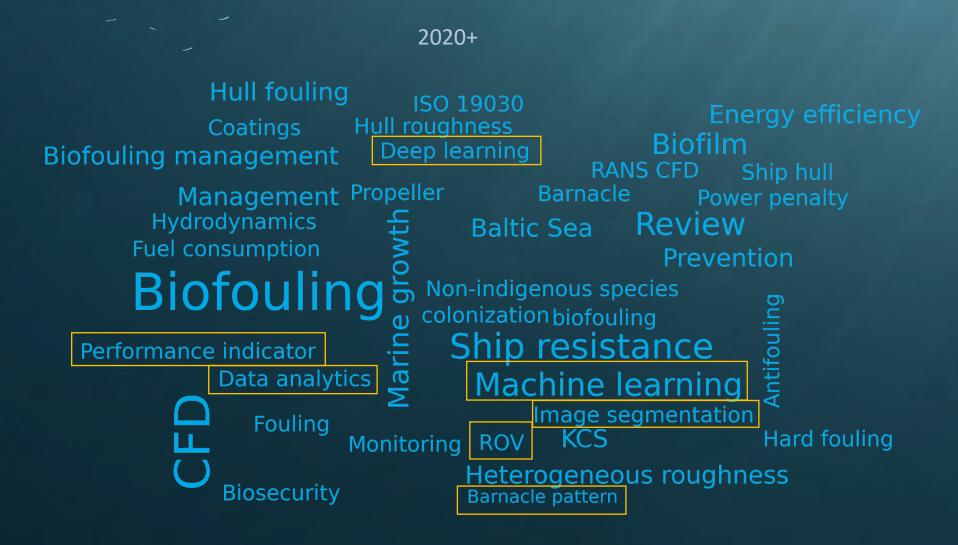


Recreational vessels

Antifouling Coatings Machine learning Metted surface area biofouling Antifouling Ship drag Barnacle fouling Marine fouling Hybrid ferry Powering Docking period Shipping Adhesion strength Adhesion strength Ship resistance Fuel consumption Hull fouling Added resistance Added resistance Hull fouling Added resistance Fuel consumption Hull fouling Added resistance Ballast water Life-cycle assessment ISO 19030 Simulation Fouling control Invasive species

Propeller

2010-19





17 studies 1-3 ship

15 studies > 5 Ships

Max -> 80 ships

3rd quartile 21 ship

Average 17 ships

SUM 489 Ships



13 underwater image enhancement



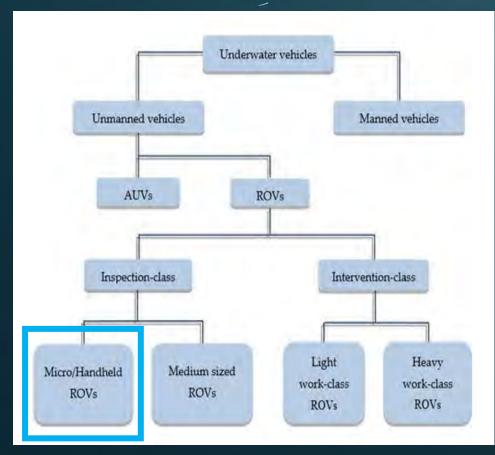
11 image segmentation underwater





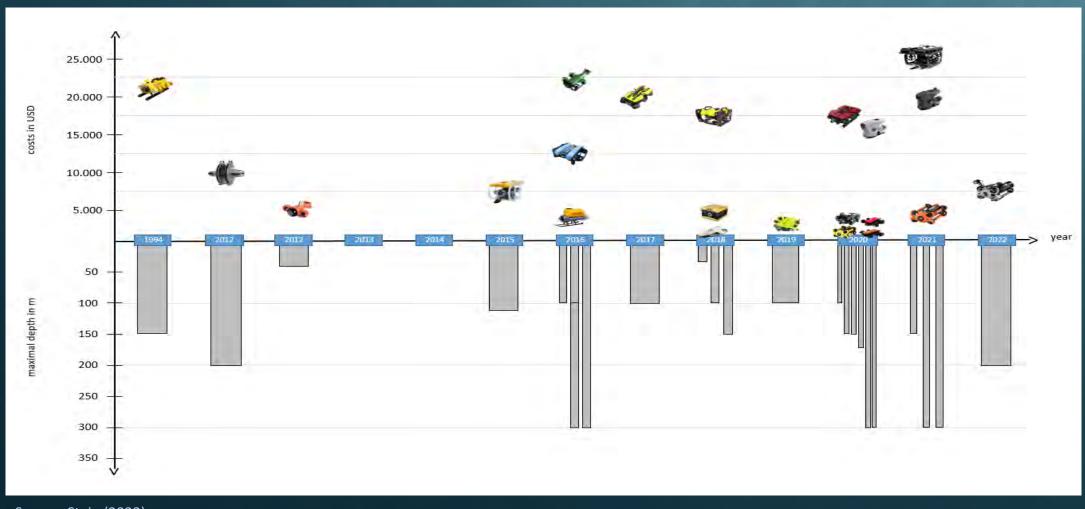
A Brief ROV Market Overview

Micro ROV Overview





Capocci et al. (2017)



Source: Stein (2023)

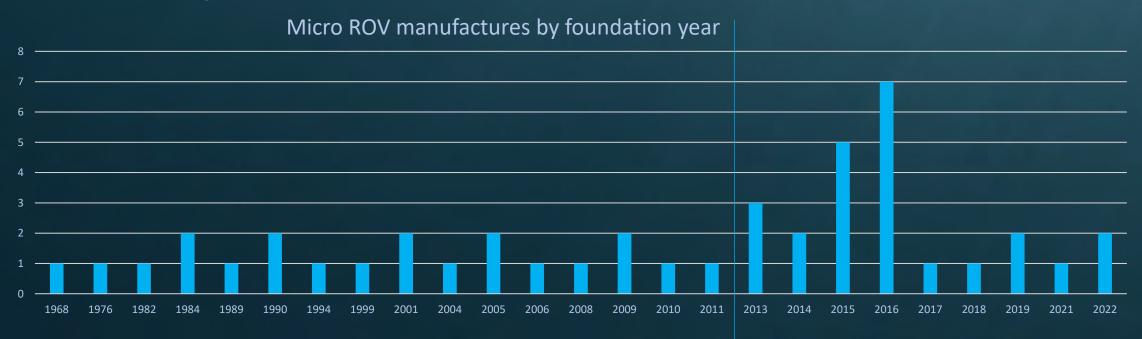
Micro ROV Market Overview

Stein (2023) 22 most prominent micro systems

Kingma et al. (2025) 88 ROV Systems micro and intervention class

Complete Market Overview on micro ROV systeme 2025

- -> 48 manufacteurs
- -> 133 micro ROV systems



Market Observation most predominant ROVs



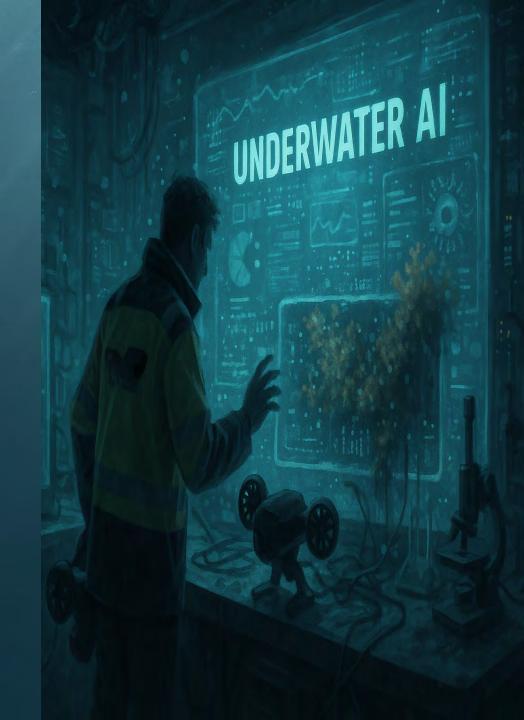




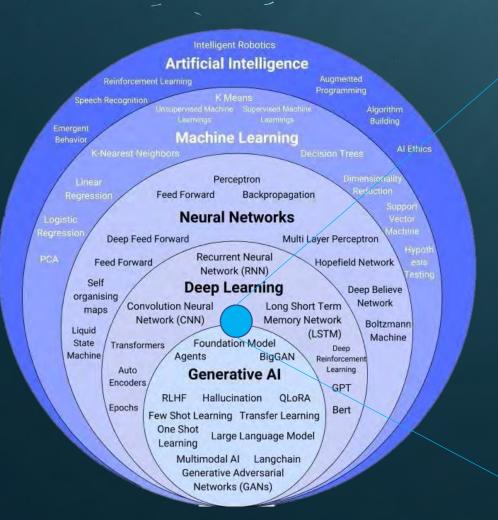


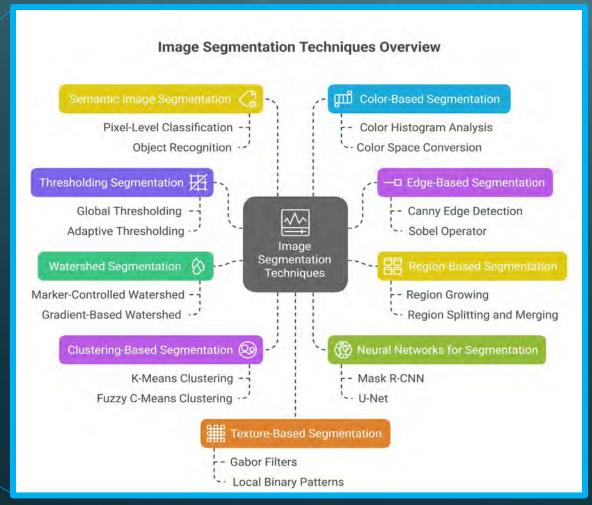


Image Segmentation Architecture Model Comparison



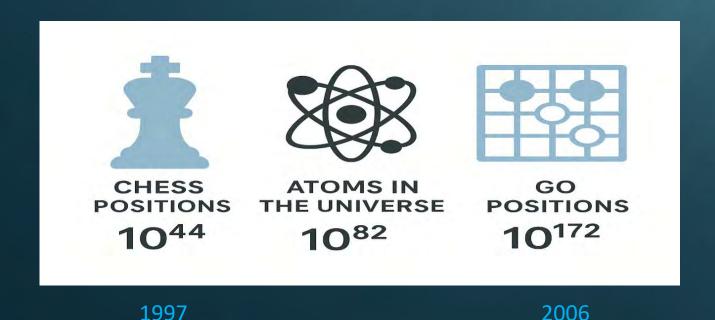
Understand Al BEFORE We Talk About It





Source: Abdelnaser (2024)

Understand The Magnitude



AlphaGo vs. Sedol

Deep Blue vs. Kasparov

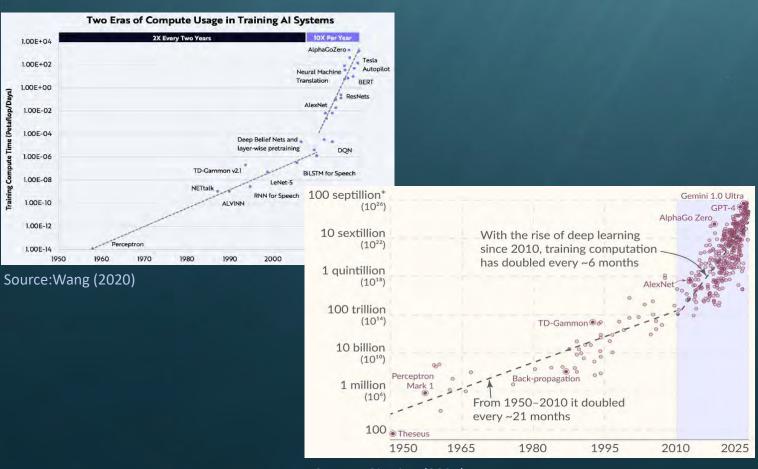
25 years ago, successful Al calculation exceeded the handling of amount of atoms in the universe...

... how hard can it be to predict biofouling growth patterns on tiny box shapes (ships) in a confined space (oceans)...

... if we ask the right questions?

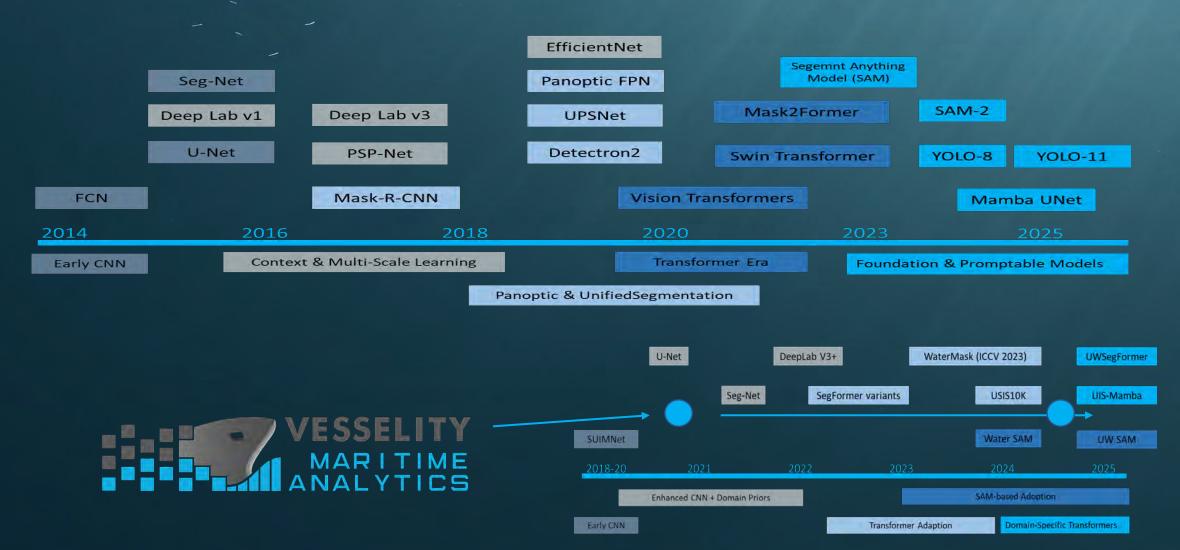
Understand Al BEFORE You Talk About It





Source: Giattino (2024)

Overview of Image Segmentation Architectures



Al Data 2021

	Precision	MIoU	Data
Bloomfield et al (2021)	0.7960	-	10.263
Islan et al. (2020)	0.8697	0.8414	1.525
O'Byrne et al. (2018)	0.9400	0.8700	2.500
Liu & Fang (2020)	- 7	0.6465	2.237
Our approach	0.9500	0.8500	1.128

Chin et al (2021) identified a variety of marine growth including lkelp and oysters etc.

Architecture	MIoU*	data
PSPNet	.45	
Simple Unet	.51	
Unet with encoder	.54	1.128
SUIMNet with encoder	.73	
Our approach	.85	

Marine Fouling Image Segmentation

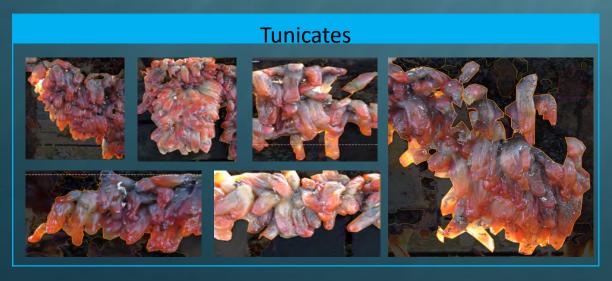


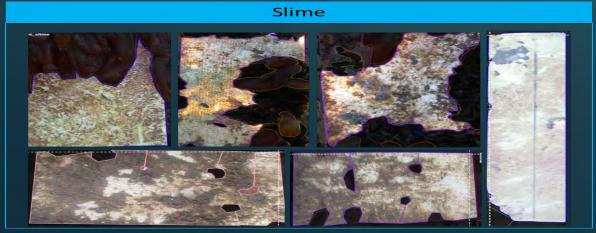
The key to successful underwater AI analysis lies in the labeling of the core training data. This process must be correct, accurate and consistent to achieve valid and robust results.

Technical Demo Examples

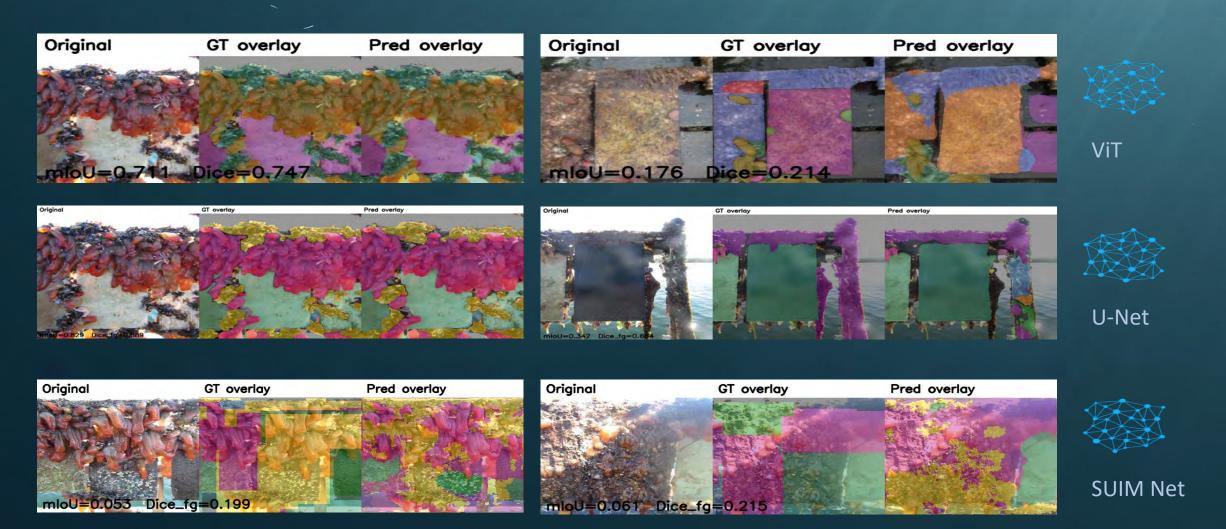




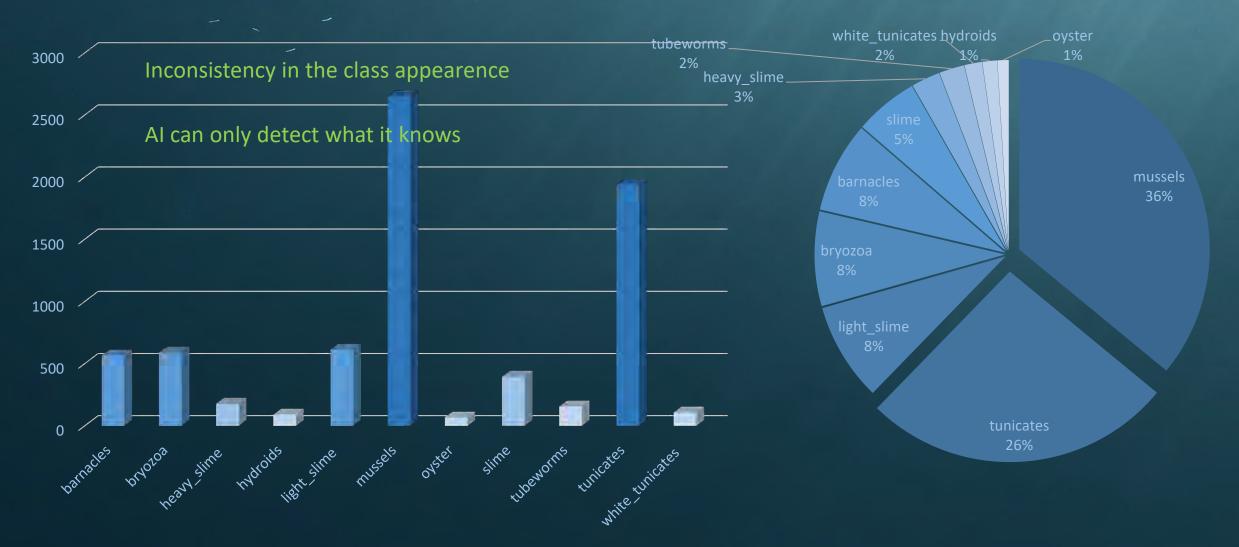




Marine Fouling Image Segmentation



Labelling classes summary

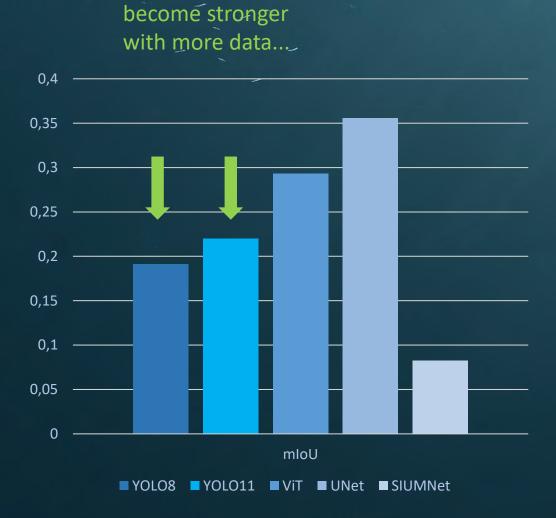


Comparison Summary Label Class

	YOLO 8	YOLO 11	Vision Transformer	UNet	SIUMNet
Year	2024	2025	2020	2015	2018
Global mIoU	0.191000	0.220000	0.293050	0.355979	0.080257
Pixel accuracy	0.335000	0.335000	0.679211	0.756594	-
Average FPS	92.000	96.000	79.811	40.332	75.109
background	0.020000*	0.020000*	0.552615	0.627898	0.105474
Barnacles	0.280000	0.440000	0.278368	0.270012	0.015103
Bryozoa	0.270000	0.500000	0.099924	0.212970	0.000000
heavy_slime	0.200000	0.240000	0.241472	0.266231	0.005831
Hydroids	0.010000	0.120000	0.192138	0.180790	0.055604
light_slime	0.320000	0.410000	0.663962	0.760580	0.293367
Mussels	0.450000	0.290000	0.513417	0.723532	0.275035
Oyster	0.000000	0.000000	0.000000	0.000000	0.000000
Slime	0.170000	0.220000	0.331678	0.468613	0.030817
Tubeworms	0.000000	0.000000	0.000000	0.000000	0.000000
Tunicates	0.580000	0.440000	0.643021	0.761122	0.261727
white_tunicates	0.000000	0.000000	0.000000	0.000000	0.000377

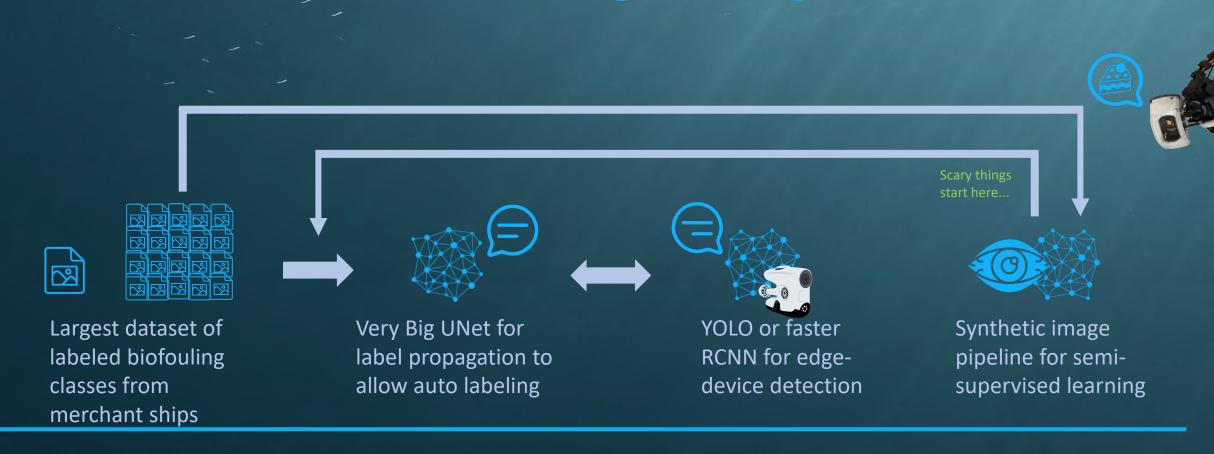
^{*} YOLO ignores the background, non comparible

Comparison Summary Label Class





The Al Solution to Biofouling Management



We intent to have the largest underwater image dataset of labeled biofouling on ships

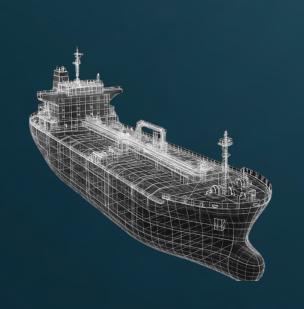
Apply strong but slow Unet characteristics in the labeling process The super fast detection speed will allow for edge device application (ROV, Smartphone)

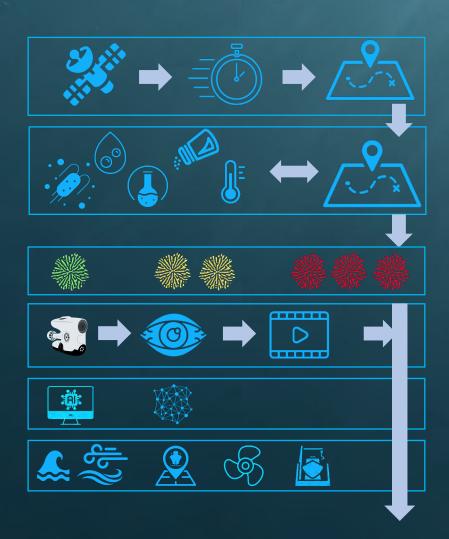
Solves the limited data issue. System will train itself after a while.

Capturing data to understanding biofouling



Our Approach





Routing Factors

Environmental Factors

Biofouling Risk Factor

Confirming ROV inspection

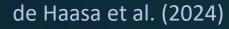
Al Data Extraction

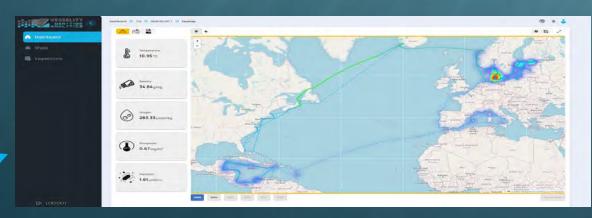
Performance Factors



Updated Greybox Model Approach

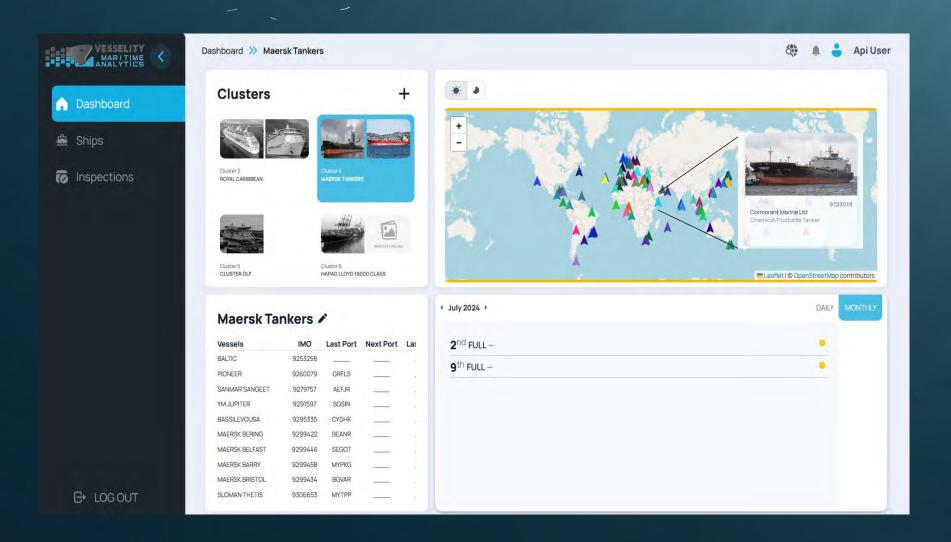
Input	Unit
White-box prediction	[kW]
Ship speed	[knots]
Ship direction	[°]
Wave height	[m]
Wave direction	[°]
Wave period	[s]
Wind speed	[m/s]
Wind direction	[°]
Average sea surface temperature	l°C1
Anchorage days since clean ship	[days]
Sailing days since clean ship	[days]
Average ship speed	[knots]
Mean roll	[°]
Mean pitch	[°]
Roll deviation	[°/s]
Pitch deviation	[°/s]
Output	Unit
Fouled ship power	[kW]

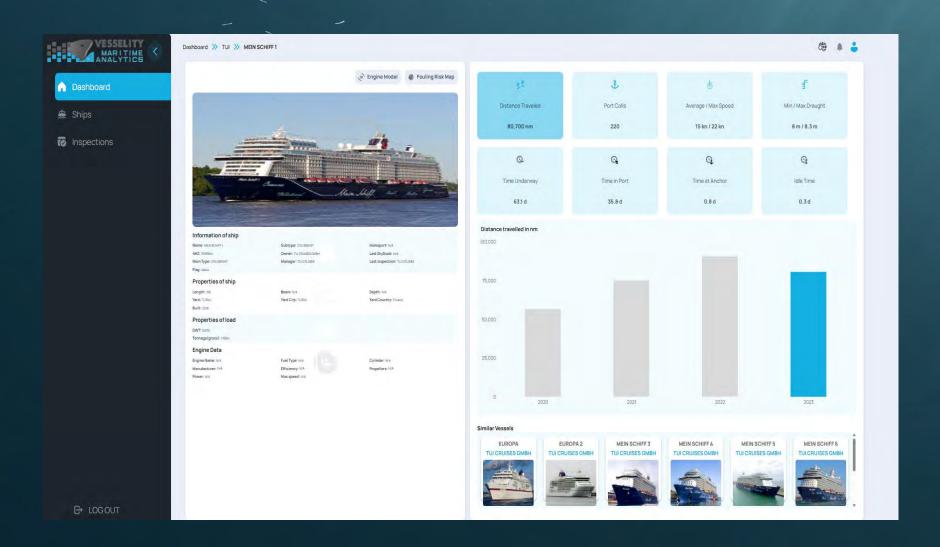




Advanced live routing evaluation based on time and speed

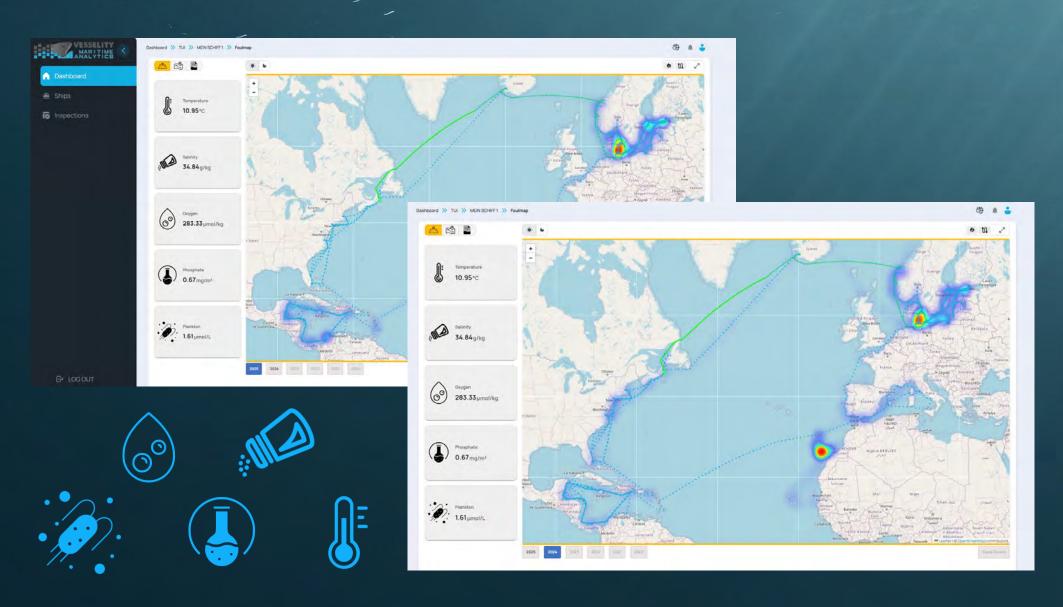
Additional Biofouling Factors	
Chlorophyll (mg/m³)	
Iron (nmol/L)	
Phyto (mg C/m³)	
Oxygen (μmol/kg)	
Ph	
Phytoplankton (mg/m³)	
Phosphate (μmol/L)	
Silicate (μmol/L)	
Salinity (g/kg)	
Temperature (°C)	

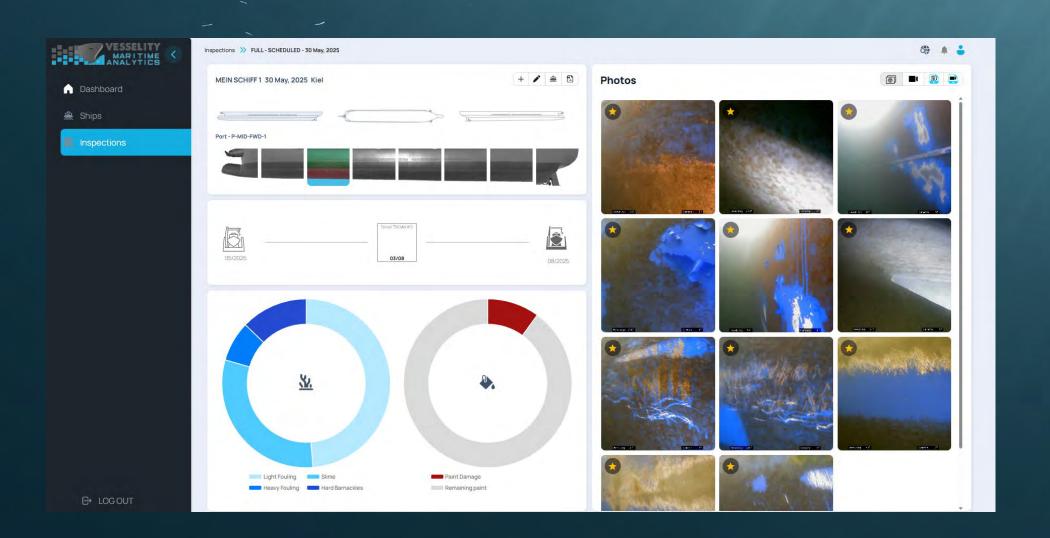










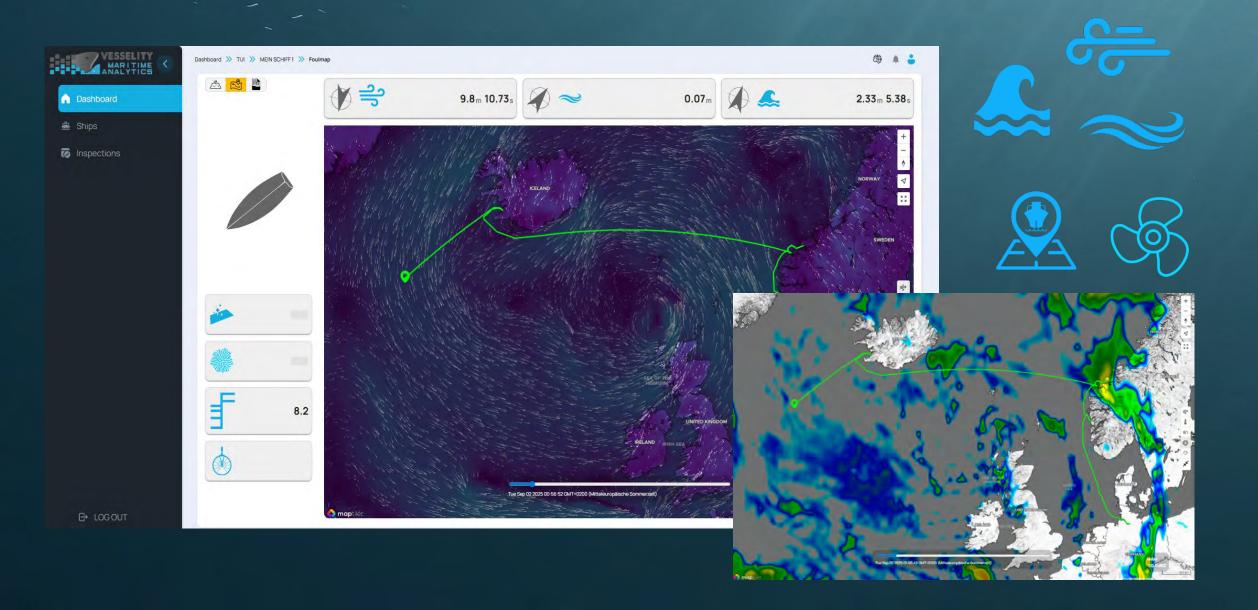












What comes next?

Biofouling Training Image Sythetisation



Synthetic image pipeline for semisupervised learning

Synthetic image pipeline for semi-supervised learning

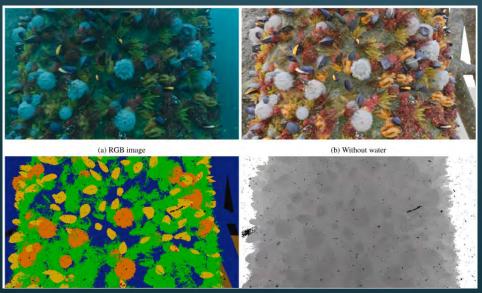


In the near future, we will have our AI network train itself on synthetic training images of biofouling.

Barbosa and Apolinario (2025)



Mai et al. (2024)

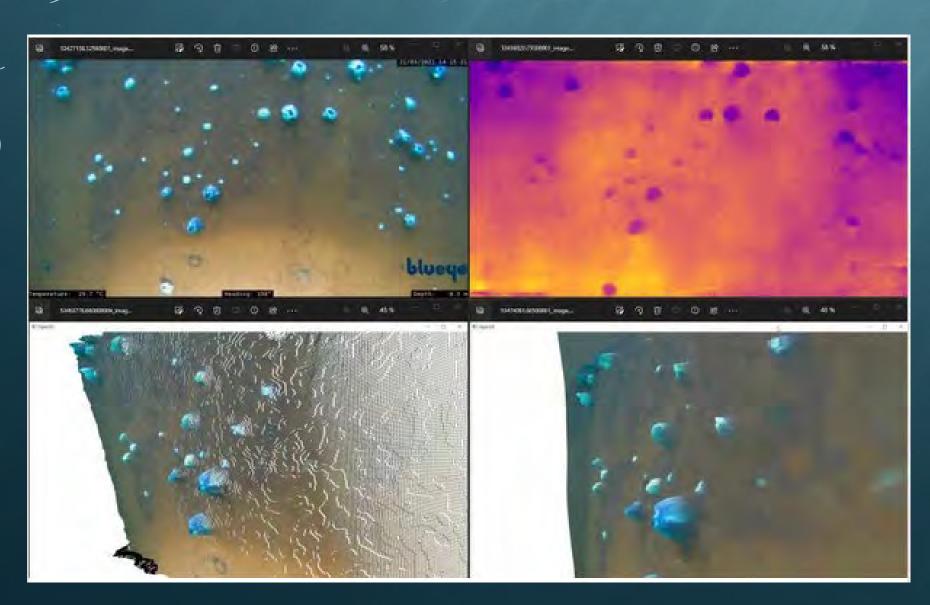


Neural Radience Fields

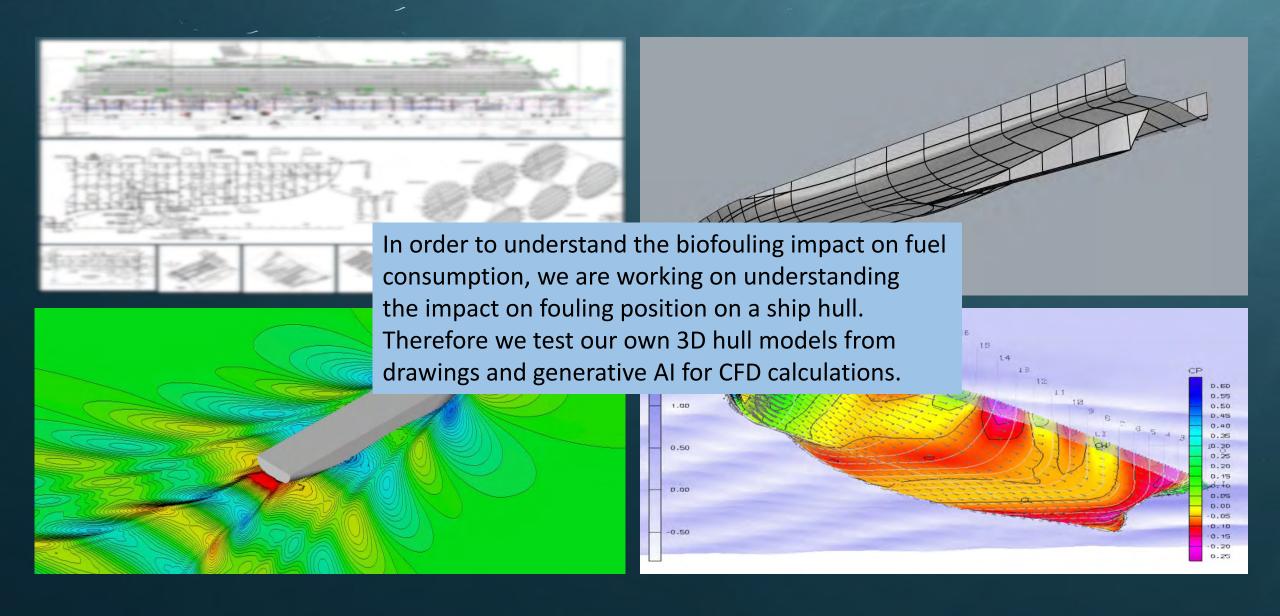
By applying a technique in Al image manipulation called Neural Radience Fields (NeRF) we are able to extract/ estimate 3D depth information from 2D inspection images, by image depth map generation.



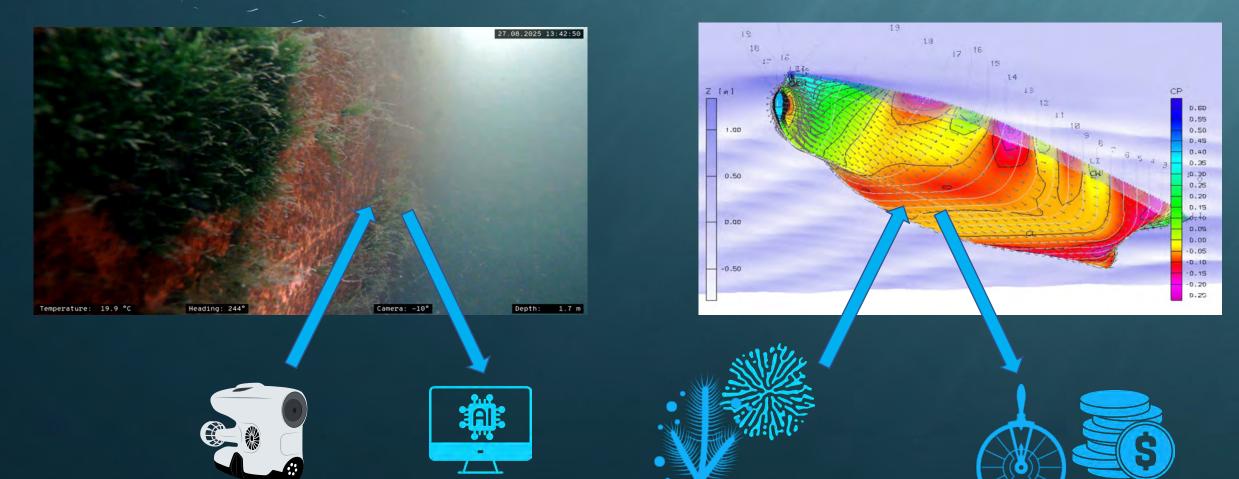
With additional research, this will allow us to understand the size of biofouling on a ship hull.



Reverse Engineered CDF Models



SLAM Projection



??? V-SLAM
??? LIFT-SLAM (introduced by Bruno and Colombini, 2021)

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